RTCA, Inc. 1828 L Street, NW, Suite 805 Washington, DC 20036-5133, USA

Minimum Operational Performance Standards for

Air Traffic Control Radar Beacon System (ATCRBS)
Airborne Equipment

DRAFT Version 0.5b

Prepared by: SC-209

© 2007, RTCA, Inc.

RTCA/DO-144A MM DD, 2007

Supersedes: RTCA/DO-144

Copies of this document may be obtained from

RTCA, Inc. 1828 L Street, NW, Suite 805 Washington, DC 20036-5133, USA

> Telephone: 202-833-9339 Facsimile: 202-833-9434 Internet: www.rtca.org

Please call RTCA for price and ordering information

FOREWORD

These Minimum Operational Performance Standards (MOPS) were prepared by RTCA Special Committee 209 (SC-209) and approved by the RTCA Program Management Committee (PMC) on MM DD, YYYY. This document represents the consolidated performance requirements from two sources; RTCA/DO-144, "Minimum Operational Characteristics for Airborne ATC Transponder Systems," dated March 12, 1970, and Change 1 to DO-144, posted as RTCA Paper No. 232-70/EC-643, dated November 5, 1970, and the performance standards referred to in paragraph (a)(1) of Federal Aviation Administration (FAA) Technical Standard Order (TSO) -C74c, dated February 20, 1973. The performance standards of this document also reflects current ICAO Annex 10, Volume IV, Chapter 3 requirements for airborne systems having only Mode A and Mode C capabilities.

RTCA, Incorporated is a not-for-profit corporation formed to advance the art and science of aviation and aviation electronic systems for the benefit of the public. The organization functions as a Federal Advisory Committee and develops consensus-based recommendations on contemporary aviation issues. RTCA's objectives include, but are not limited to:

- Coalescing aviation system user and provider technical requirements in a manner that helps government and industry meet their mutual objectives and responsibilities;
- Analyzing and recommending solutions to the system technical issues that aviation faces as it continues to pursue increased safety, system capacity and efficiency;
- Developing consensus on the application of pertinent technology to fulfill user and provider requirements, including development of Minimum Operational Performance Standards (MOPS) for electronic systems and equipment that support aviation; and
- Assisting in developing the appropriate technical material upon which positions for the International Civil Aviation Organization (ICAO) and the International Telecommunication Union (ITU) and other appropriate international organizations can be based.

The recommendations of RTCA are often used as the basis for government and private sector decisions as well as the foundation for new FAA Technical Standard Orders.

Since RTCA is not an official agency of the United States Government, its recommendations may not be regarded as statements of official government policy unless so enunciated by the United States Government organization or agency having statutory jurisdiction over any matters to which the recommendations relate.

CHANGE HISTORY

Date / Version	Description			
	Initial version of DO-144 taken from RTCA in hardcopy only and scanned			
1/19/06, v0.1	into an electronic file, and OCRed to produce the first editable electronic			
1/19/00, vo.1	copy. Since the original DO-144 was written in Part I, Part II, Part III			
	nomenclature, this was changed to chapters and subsections.			
8/3/06, v0.2	Used to create the initial Comparison Matrix of the Outline of DO-144			
0/3/00, 10.2	versus the proposed DO-144A.			
	This is the first version of the draft of DO-144A that has been rearranged			
	into the standard RTCA MOPS format. The structure of the requirements			
	section §2.2 was modeled after that in DO-181 and the corresponding			
	information from DO-144 was copied into the appropriate section. The			
	test procedure section §2.4 was populated with the existing test			
10/11/06, v0.3	procedures from DO-144 section §2.3, while keeping the identical outline			
	as was set up for §2.2. Since there were no sections in the original DO-			
	144 dealing specifically with environmental testing, then in this draft,			
	section §2.3 was populated with standard boilerplate text from the RTCA			
	MOPS drafting standard. Section 3.0 of a standard RTCA MOPS			
	document deals with Installed Equipment and in this draft that section has			
	been populated with what was in the original DO-144 for Flight Tests in			
§2.3. (1) During the review of TSO C74c, it was discovered that there				
	"Change" document issued for DO-144, dated 11/5/70. The changes			
	identified in that Change document are implemented into this revision.			
10/31/06, v0.4	(2) It was further discovered that the current revision of the			
10/31/00, 10.4	Environmental MOPS is DO-160E. Therefore, all references to DO-160			
	in this document were changed to reference DO-160E, and the appropriate			
	paragraph reference numbers were double checked.			
12/18/06, v0.5	ATCRBS Sub-sub team inputs to Section 2.1 and 2.2.			
12/23/06, v0.5a	Added Section 2.1.10 regarding interrogator characteristics			
1/6/07, v0.5b	Inputs to Section 1.0, and added an Appendix A. place holder to insert			
1/0/07, 10.30	tables from ICAO Annex 10, Volume IV, Appendix to Chapter 3			

This Page will be Left Blank in the published version

TABLE OF CONTENTS

1 P	URPOSE AND SCOPE	<u>67</u> 6
1.1	Introduction	676
1.1.1	International Standards	
1.1.2	Preparation of Minimum Operational Performance Standards for	
1.2	System Overview	
1.3	Operational Application(s)	
1.4	Intended Function	
1.5	Operational Goals	
1.6	Assumptions	
1.7	Test Procedures	<u>898</u>
<mark>1.8</mark>	Definition of Terms	9 10 9
2 E	QUIPMENT PERFORMANCE REQUIREMENTS AND TEST	T PROCEDURES <u>111210</u>
2.1	General Requirements	11 1210
2.1.1	Airworthiness	
2.1.2	Intended Function	
2.1.3	Federal Communications Commission Rules	
2.1.4	Fire Protection	<u>121210</u>
2.1.5	Operation of Controls	<u>121210</u>
2.1.6	Accessibility of Controls	<u>121210</u>
2.1.7	Effects of Test	<u>131311</u>
2.1.8	Display of Navigation Facility Identification	Error! Bookmark not defined.
2.1.9	Design Assurance	Frron! Rookmark not defined
		Ellot. Dookinalk not uchicu.
<mark>2.2</mark>	Equipment Performance – Standard Conditions	<u>1616</u> 14
2.2.1	Equipment Performance – Standard Conditions Definition of Standard Conditions	<u>1616</u> 14 <u>1616</u> 14
2.2.1 2.2.2	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics	
2.2.1 2.2.2 2.2.2	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth	
2.2.1 2.2.2 2.2.2 2.2.3	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics	
2.2.1 2.2.2 2.2.2 2.2.3 2.2.3	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 1 Transponder Power Output	
2.2.1 2.2.2 2.2.2 2.2.3 2.2.3 2.2.3	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 1 Transponder Power Output 2 Emission of Spurious RF Energy	
2.2.1 2.2.2 2.2.2 2.2.3 2.2.3 2.2.3 2.2.4	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 1 Transponder Power Output 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space)	
2.2.1 2.2.2 2.2.2 2.2.3 2.2.3 2.2.3 2.2.4 2.2.4	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 1 Transponder Power Output 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses	
2.2.1 2.2.2 2.2.2 2.2.3 2.2.3 2.2.3 2.2.4 2.2.4 2.2.4	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 1 Transponder Power Output 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses 2 Information Pulses	
2.2.1 2.2.2 2.2.2 2.2.3 2.2.3 2.2.3 2.2.4 2.2.4 2.2.4 2.2.4	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 1 Transponder Power Output 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses 2 Information Pulses 3 Special Position Identification (SPI) Pulses	
2.2.1 2.2.2 2.2.2 2.2.3 2.2.3 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 1 Transponder Power Output 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses 2 Information Pulses 3 Special Position Identification (SPI) Pulses 4 Reply Pulse Shape	
2.2.1 2.2.2 2.2.3 2.2.3 2.2.3 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 1 Transponder Power Output 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses 2 Information Pulses 3 Special Position Identification (SPI) Pulses 4 Reply Pulse Shape 5 Reply Pulse Interval Tolerances	
2.2.1 2.2.2 2.2.3 2.2.3 2.2.3 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 1 Transponder Power Output 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses 2 Information Pulses 3 Special Position Identification (SPI) Pulses 4 Reply Pulse Shape 5 Reply Pulse Interval Tolerances 6 Reply Delay and Jitter	
2.2.1 2.2.2 2.2.3 2.2.3 2.2.3 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses 2 Information Pulses 3 Special Position Identification (SPI) Pulses 4 Reply Pulse Shape 5 Reply Pulse Interval Tolerances 6 Reply Delay and Jitter 7 Transmission Time of Special Position Identification (SPI) Pulse	
2.2.1 2.2.2 2.2.3 2.2.3 2.2.3 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.5	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 1 Transponder Power Output 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses 2 Information Pulses 3 Special Position Identification (SPI) Pulses 4 Reply Pulse Shape 5 Reply Pulse Interval Tolerances 6 Reply Delay and Jitter 7 Transmission Time of Special Position Identification (SPI) Pulses Side Lobe Characteristics	
2.2.1 2.2.2 2.2.3 2.2.3 2.2.3 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.5 2.2.5	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 1 Transponder Power Output 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses 2 Information Pulses 3 Special Position Identification (SPI) Pulses 4 Reply Pulse Shape 5 Reply Pulse Interval Tolerances 6 Reply Delay and Jitter 7 Transmission Time of Special Position Identification (SPI) Pulses Side Lobe Characteristics 1 Reply	
2.2.1 2.2.2 2.2.3 2.2.3 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.5 2.2.5 2.2.5	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 1 Transponder Power Output 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses 2 Information Pulses 3 Special Position Identification (SPI) Pulses 4 Reply Pulse Shape 5 Reply Pulse Interval Tolerances 6 Reply Delay and Jitter 7 Transmission Time of Special Position Identification (SPI) Pulses Side Lobe Characteristics 1 Reply No Reply	
2.2.1 2.2.2 2.2.3 2.2.3 2.2.3 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.5 2.2.5 2.2.5 2.2.5	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 1 Transponder Power Output 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses 2 Information Pulses 3 Special Position Identification (SPI) Pulses 4 Reply Pulse Shape 5 Reply Pulse Interval Tolerances 6 Reply Delay and Jitter 7 Transmission Time of Special Position Identification (SPI) Pulses 1 Reply 2 No Reply 3 Suppression	
2.2.1 2.2.2 2.2.3 2.2.3 2.2.3 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.5 2.2.5 2.2.5 2.2.5 2.2.5	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses 2 Information Pulses 3 Special Position Identification (SPI) Pulses 4 Reply Pulse Shape 5 Reply Pulse Interval Tolerances 6 Reply Delay and Jitter 7 Transmission Time of Special Position Identification (SPI) Pulse Side Lobe Characteristics 1 Reply 2 No Reply 3 Suppression Pulse Decoder Characteristics	
2.2.1 2.2.2 2.2.3 2.2.3 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.5 2.2.5 2.2.5 2.2.5 2.2.6 2.2.6	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses 2 Information Pulses 3 Special Position Identification (SPI) Pulses 4 Reply Pulse Shape 5 Reply Pulse Interval Tolerances 6 Reply Delay and Jitter 7 Transmission Time of Special Position Identification (SPI) Pulse Side Lobe Characteristics 1 Reply 2 No Reply 3 Suppression Pulse Decoder Characteristics 1 Receiver Sensitivity and Dynamic Range	$\begin{array}{c} 000000000000000000000000000000000000$
2.2.1 2.2.2 2.2.3 2.2.3 2.2.3 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.4 2.2.5 2.2.5 2.2.5 2.2.5 2.2.5	Equipment Performance – Standard Conditions Definition of Standard Conditions Receiver Characteristics 1 Transponder Receiver Bandwidth Transmitter Characteristics 2 Emission of Spurious RF Energy Reply Pulse Characteristics (Signals in Space) 1 Framing Pulses 2 Information Pulses 3 Special Position Identification (SPI) Pulses 4 Reply Pulse Shape 5 Reply Pulse Interval Tolerances 6 Reply Delay and Jitter 7 Transmission Time of Special Position Identification (SPI) Pulses 1 Reply 2 No Reply 3 Suppression Pulse Decoder Characteristics 1 Receiver Sensitivity and Dynamic Range	

2.2.7.2 Echo Suppression and Recovery	· · · · · · · · · · · · · · · · · · ·
2.2.7.3 Reply Rate	
2.2.8 Response in the Presence of Interference	
2.2.9 Undesired Replies Error! Book	
2.2.10 Transponder Self Test and Monitor	<u>232320</u>
2.2.10.1 Manual Self-Test	
2.2.10.2 Automatic Self-Test	· · · · · · · · · · · · · · · · · · ·
2.2.11 Response in Mutual Suppression Pulses	
2.2.12 Diversity Error! Book	
2.2.13 Data Handling and Interfaces	· · · · · · · · · · · · · · · · · · ·
2.2.13.1 Code Nomenclature	<u>242321</u>
2.2.13.2 Identification	
2.2.13.3 Pressure Altitude Transmissions	
2.2.14 ATCRBS Transponder	
2.2.15 Antennas	
2.2.15.1 Frequency	<u>252522</u>
2.2.15.2 Impedance and VSWR	2 <u>525</u> 23
2.2.15.3 Polarization Polarization	
2.2.15.4 Radiation Pattern	
2.2.16 Power	<u>252523</u>
2.2.16.1 Cold Start Error! Book	mark not defined.
2.2.16.2 Interruption	2 <u>52523</u>
2.3 Equipment Performance – Environmental Conditions	<u>272624</u>
2.3.1 Temperature and Altitude Tests (RTCA/DO-160E, Section 4.0)	<u>272624</u>
2.3.1.1 Low Operating Temperature Test	<u>272624</u>
2.3.1.2 High Short-Time Operating Temperature Test	<u>272624</u>
2.3.1.3 High Operating Temperature	<u>272624</u>
2.3.1.4 In-Flight Loss of Cooling	
2.3.1.5 Altitude Tests	
2.3.1.6 Decompression Test	
2.3.1.7 Overpressure Test	
2.3.2 Temperature Variation Test (RTCA/DO-160E, Section 5.0)	· · · · · · · · · · · · · · · · · · ·
2.3.3 Humidity Test (RTCA/DO-160E, Section 6.0)	· · · · · · · · · · · · · · · · · · ·
2.3.4 Shock Tests (RTCA/DO-160E, Section 7.0)	
2.3.4.1 Operational Shocks	
2.3.4.2 Crash Safety Shocks	
2.3.5 Vibration Tests (RTCA/DO-160E, Section 8.0)	
2.3.6 Explosion Test (RTCA/DO-160E, Section 9.0)	
2.3.7 Waterproofness Test (RTCA/DO-160E, Section 10.0)	
2.3.7.1 Drip Proof Test	
2.3.7.2 Spray Proof Test	
2.3.7.3 Continuous Stream Proof Test	
2.3.8 Fluids Susceptibility Tests (RTCA/DO-160E, Section 11.0)	
2.3.8.1 Spray Test	
2.3.8.2 Immersion Test	
2.3.9 Sand and Dust Test (RTCA/DO-160E, Section 12.0)	202027
2.3.10 Fungus Resistance Test (RTCA/DO-160E, Section 13.0)	<u>302927</u>
2.3.11 Salt Spray Test (RTCA/DO-160E, Section 14.0)	<u>3029</u> 27 <u>3029</u> 27
2.3.11 Salt Spray Test (RTCA/DO-160E, Section 14.0)2.3.12 Magnetic Effect Test (RTCA/DO-160E, Section 15.0)	3 <u>029</u> 27 3 <u>029</u> 27 3 <u>029</u> 27
 2.3.11 Salt Spray Test (RTCA/DO-160E, Section 14.0) 2.3.12 Magnetic Effect Test (RTCA/DO-160E, Section 15.0) 2.3.13 Power Input Tests (RTCA/DO-160E, Section 16.0) 	302927 302927 302927 303028
 2.3.11 Salt Spray Test (RTCA/DO-160E, Section 14.0) 2.3.12 Magnetic Effect Test (RTCA/DO-160E, Section 15.0) 2.3.13 Power Input Tests (RTCA/DO-160E, Section 16.0) 2.3.13.1 Normal Operating Conditions 	302927 302927 302927 303028 303028
 2.3.11 Salt Spray Test (RTCA/DO-160E, Section 14.0) 2.3.12 Magnetic Effect Test (RTCA/DO-160E, Section 15.0) 2.3.13 Power Input Tests (RTCA/DO-160E, Section 16.0) 	302927 302927 302927 303028 303028 313028

2.3.14.1 Category A Requirements (If Applicable)	<u>313028</u>
2.3.14.2 Category B Requirements (If Applicable)	313028
2.3.15 Audio Frequency Conducted Susceptibility Test (RTCA/DO-160E, Section 18.0)	
2.3.16 Induced Signal Susceptibility Test (RTCA/DO-160E, Section 19.0)	313028
2.3.17 Radio Frequency Susceptibility Test (RTCA/DO-160E, Section 20.0)	313128
2.3.18 Emission of Radio Frequency Energy Test (RTCA/DO-160E, Section 21.0)	
2.3.19 Lightning Induced Transient Susceptibility Test (RTCA/DO-160E, Section 22.0)	
2.4 Equipment Test Procedures	
2.4.1 Definitions of Terms and Conditions of Test (§2.2.1)	32 3129
2.4.2 Verification of Receiver Characteristics (§2.2.2)	
2.4.2.1 Verification of Transponder Receiver Bandwidth (§2.2.2.1)	
2.4.3 Verification of Transmitter Characteristics (§2.2.3)	
2.4.3.1 Verification of Transponder Power Output (§2.2.3.1)	343331
2.4.3.2 Verification of Emission of Spurious RF Energy (§2.2.3.2)	
2.4.4 Verification of Reply Pulse Characteristics (Signals in Space) (§2.2.4)	
2.4.4.1 Verification of Framing Pulses (§2.2.4.1)	
2.4.4.2 Verification of Information Pulses (§2.2.4.2)	353432
2.4.4.3 Verification of Special Position Identification (SPI) Pulses (§2.2.4.3)	<u>353432</u>
2.4.4.4 Verification of Reply Pulse Shape (§2.2.4.4)	<u>363533</u>
2.4.4.5 Verification of Reply Pulse Interval Tolerances (§2.2.4.5)	<u>363533</u>
2.4.4.6 Verification of Reply Delay and Jitter (§2.2.4.6)	<u>3736</u> 34
2.4.4.7 Verification of Transmission Time of Special Position Identification (SPI) Pulse (§2.2.4	1.7)
373634	
2.4.5 Verification of Side Lobe Characteristics (§2.2.5)	<u>383735</u>
2.4.5.1 Verification of Reply (§2.2.5.1)	<u>383735</u>
2.4.5.2 Verification of No Reply (§2.2.5.2)	<u>393836</u>
2.4.5.3 Verification of Suppression (§2.2.5.3)	<u>393836</u>
2.4.6 Verification of Pulse Decoder Characteristics (§2.2.6)	<u>403937</u>
2.4.6.1 Verification of Receiver Sensitivity and Dynamic Range (§2.2.6.1)	<u>403937</u>
2.4.6.2 Verification of Pulse Duration Discrimination (§2.2.6.2)	<u>414038</u>
2.4.7 Verification of Desensitization and Recovery Characteristics (§2.2.7)	<u>424139</u>
2.4.7.1 Verification of Dead Time (§2.2.7.1)	<u>424139</u>
2.4.7.2 Verification of Echo Suppression and Recovery (§2.2.7.2)	<u>4341</u> 39
2.4.7.3 Verification of Reply Rate (§2.2.7.3)	<u>4443</u> 41
2.4.8 Verification of Response in the Presence of Interference (§2.2.8)	
2.4.9 Verification of Undesired Replies (§2.2.9)	
2.4.10 Verification of Transponder Self-Test and Monitor (§2.2.10)	<u>4544</u> 42
2.4.10.1 Verification of Manual Self-Test (§2.2.10.1)	
2.4.10.2 Verification of Automatic Self-Test (§2.2.10.2)	
2.4.11 Verification of Response in Mutual Suppression Pulses (§2.2.11)	
2.4.12 Verification of Diversity (§2.2.12)	
2.4.13 Verification of Data Handling and Interfaces (§2.2.13)	
2.4.13.1 Verification of Code Nomenclature (§2.2.13.1)	
2.4.13.2 Verification of Identification (§2.2.13.2)	
2.4.13.3 Verification of Pressure Altitude Transmissions (§2.2.13.3)	<u>4847</u> 45
2.4.14 Verification of ATCRBS Transponder (§2.2.14)	<u>4948</u> 46
2.4.15 Antennas (§2.2.15)	
2.4.15.1 Verification of Frequency (§2.2.15.1)	<u>5048</u> 46
2.4.15.2 Verification of Impedance and VSWR (§2.2.15.2)	<u>5048</u> 46
2.4.15.3 Verification of Polarization (§2.2.15.3)	<u>5048</u> 47
2.4.15.4 Verification of Radiation Pattern (§2.2.15.4)	
2.4.16 Verification of Power (§2.2.16)	
2.4.16.1 Verification of Cold Start (§2.2.16.1)	<u>5149</u> 47

<mark>2.4.16.</mark>	Verification of Interruption (§2.2.16.2)	<u>5149</u> 47
3 IN	STALLED EQUIPMENT PERFORMANCE	<u>535150</u>
21 5		505150
	Equipment Installation	
3.1.1	Equipment Accessibility	
3.1.2	Inadvertent Turn Off	
3.1.3	Displays	
3.1.4	Aircraft Power Source	
3.1.5	Transmission Line(s)	
3.1.6	Antenna Location	
3.1.7	Mutual Suppression	
	Conditions of Test	
3.2.1	Power Input	
3.2.2	Interference Effects	
3.2.3	Environment	
3.2.4	Adjustment of Equipment	
3.2.5	Warm-up Period	
3.2.6	Radiation Pattern	
3.3 T 3.3.1	Conformity Inspection	
3.3.2	Conformity Inspection	
	Bench Tests	
3.3.3	Reply Frequency	
3.3.4	Framing Pulse Spacing	
3.3.5	Reply Codes.	
3.3.6	Pressure Altitude Transmissions.	
3.3.7	Altitude Reporting Test	
3.3.8	Reply Pulse Width	
3.3.9 3.3.10	Receiver Sensitivity	
	Transmitter Power Output	
3.3.11	Mode S Address	
3.3.12 3.3.13	Received Reply	
3.3.14	Airspeed Fixed Field	
3.3.15	On-the-Ground Condition	
	Diversity Antenna Installations	
3.4 F 3.4.1	Flight Test Procedures	
	Ground Pre-Flight Tests	
3.4.2	Operational Flight Tests	<u>020039</u>
4 EQ	QUIPMENT OPERATIONAL PERFORMANCE CHARACTERISTICS	646361
- EC	WILLIAM OF EXACIONAL PERFORMANCE CHARACTERISTICS	<u>0403</u> 01
4.1 R	Required Operational Performance Requirements	<u>646361</u>
4.1.1	Power Inputs	
4.1.2	Equipment Operating Modes	
4.1.3	Continue with Other Operational Requirements as Necessary	
	Cest Procedures for Operational Performance Requirements	
4.2.1	Power Input	
4.2.2	Equipment Operating Modes	
423	Continue with Other Test Procedures	646361

This Page Intentionally Left Blank

1 PURPOSE AND SCOPE

1.1 Introduction

This document sets forth minimum operational performance standards for Air Traffic Control Radar Beacon System (ATCRBS) airborne equipment. Incorporated within these standards are system characteristics that will be useful to users of the system as well as designers, manufacturers and installers. These performance standards represent a consolidation of performance requirements from two sources; RTCA/DO-144, "Minimum Operational Characteristics for Airborne ATC Transponder Systems," dated March 12, 1970, and Change 1 to DO-144, posted as RTCA Paper No. 232-70/EC-643, dated November 5, 1970, and the performance standards referred to in paragraph (a)(1) of Federal Aviation Administration (FAA) Technical Standard Order (TSO) -C74c, dated February 20, 1973.

Compliance with the following MOPS is required to achieve at least that minimum performance on which control and separation of aircraft is based and to insure against derogation of service to other users of aviation navigation and communication services. These MOPS are applicable to all users of airborne ATC transponder systems who are required by regulation to participate in the ATC system or who voluntarily choose to do so.

Note: The use of "shall" in the body of this document indicates a requirement. The use of "should" indicates a characteristic that is highly recommended, but is not required.

It is recognized that any regulatory application of these standards is the responsibility of appropriate government agencies.

Because the measured values of equipment performance characteristics may be a function of the measurement method, standard test conditions and methods of test are recommended in this document.

This document considers an equipment configuration consisting of: transponder, control panel, antenna and interconnecting cables. It should not be inferred that all ATCRBS airborne equipment will necessarily include all of the foregoing components as separate units; this will depend on the design configuration chosen by the manufacturer.

If the equipment implementation includes a computer software package, the guidelines contained in the most current issue of RTCA/DO-178, Software Considerations in Airborne Systems and Equipment Certification, should be considered.

1.1.1 International Standards

The performance standards of this document also reflect current International Civil Aviation Organization (ICAO) Annex 10, Volume IV, Chapter 3 requirements for airborne systems having only Mode A and Mode C capabilities. [need to check current amendment]

1.1.2 Preparation of Minimum Operational Performance Standards for Airborne Systems

The Federal Aviation Administration is the responsible agency for certain aviation standards. However, FAA's regulatory effort is vastly improved by intelligent utilization of government/industry working arrangements, by which a variety and wealth of talent may be brought to bear on the development of a particular minimum requirement.

Therefore, to implement the concepts that have been outlined, RTCA established Special Committee 209 to update the Minimum Operational Performance Standards for Airborne Transponder System Elements (both ATCRBS and Mode S), together with a method of demonstration of compliance. However, as pointed out in these concepts, concise statements of system characteristics are a prerequisite to meaningful minimum operational characteristics for airborne systems. Accordingly, SC-209 was directed to consider such system characteristics that exist and to include them in its reports. If none exist, best assumptions were to be formulated by SC-209 and included in the reports.

1.2 The ATCRBS Secondary Surveillance Radar (SSR) Environment

Although the trend towards equipage of ATCRBS/Mode Select (S) capable transponders is increasing, a large number of aircraft are still equipped with ATCRBS-only capable transponders. Since In terms of exposure to the ATC system, this implementation is estimated to be greater than 90 percent [was 90% when Mode S MOPS came out, probably lower now...needs an updated, but "highly-accurate" Tech Center estimate] of the hours flownMode S transponders are required on aircraft with TCAS, Mode S transponders are installed on a large segment of the aircraft population. General Aviation aircraft continue to represent the largest percentage of the aircraft in the airspace and ATCRBBS transponders are still the dominant equipage for these aircraft.

The primary purpose of the ATCRBS transponder is to support ATC secondary surveillance radar (SSR) requirements. The ATCRBS SSR environment consists of the airborne ATCRBS transponders, ground interrogator-receiver, processing equipment, and an antenna system. The antenna may or may not be associated with, or slaved to, a primary surveillance radar. In operation, an interrogation pulse-pair transmitted from the interrogator-transmitter unit, via an antenna assembly, triggers each airborne transponder located in the direction of the main beam, causing a multiple pulse reply group to be transmitted from each transponder. These replies are received by the ground receiver and, after processing, are displayed to the controller. Measurement of the round-trip transit time determines the range (rho) to the replying aircraft while the mean direction of the main beam of the interrogator antenna, during the reply, determines the azimuth (theta). Based on the time spacing of the interrogation pulse-pair transmitted, the airborne transponder provides a multiple-pulse reply that represents either an individualized identity code (Mode A reply) or the aircraft's current pressure altitude (Mode C reply).

The ATCRBS transponder also replies to airborne Mode A and Mode C interrogators, thereby making its presence known to aircraft that are equipped with Traffic advisory and Collision Avoidance System (TCAS) or Airborne Collision Avoidance System (ACAS).

Additional information on ground and airborne interrogator characteristics is contained in Section 2.1.10.

1.61.3 Assumptions

[Don't know if there are any assumptions that need to be addressed. Mode S had future expansion assumptions... ATCRBS may someday be eliminated...maybe we should assume that!] This document defines the basic surveillance and link characteristics of ATCRBS transponders. Adherence to the requirements of this document will meet the needs of the airspace for surveillance of aircraft so equipped. There is no upgrade path for the ATCRBS system going forward as surveillance needs of the future may rely on different technologies.

1.71.4 Test Procedures

The specified test procedures and associated limits are intended as one means of demonstrating compliance with the minimum acceptable performance parameters. Although specific test procedures are cited, it is recognized that other methods may be preferred by the test organization. These alternate methods may be used if they provide at least equivalent information. In such cases, the procedures cited should be used as one criterion in evaluating the acceptability of the alternate procedures.

The order of tests suggests that the equipment be subjected to a succession of different tests as it moves from design and design qualification into operational use. For example, the equipment should have demonstrated compliance with the requirements of Section 2.0 as a precondition to satisfactory completion of the installed system tests of Section 3.0.

Three types of test procedures are included which should be used at different stages in the equipment approval cycle. These are discussed in the following paragraphs.

1.4.1 Environmental Tests

Environmental tests are specified in Subsection 2.3. The procedures and their associated limit requirements are intended to provide a means of determining the electrical and mechanical performance of the equipment under environmental conditions expected to be encountered in actual operations. Equipment manufacturers may use test results as design guidance in preparation of installation instructions and, in certain cases, for obtaining formal approval of equipment design and manufacture.

1.4.2 Detailed Test Procedures

Detailed test procedures are specified in Subsection 2.4. These tests are conducted at the equipment level and are intended to provide a laboratory means of demonstrating compliance with the requirements of Subsections 2.1 and 2.2. Equipment manufacturers may use test results as design guidance, for monitoring manufacturing compliance and, in certain cases, for obtaining formal approval of equipment design and manufacture.

1.4.3 Installed System Tests

The installed system test procedures and their associated requirements are specified in Section 3.0. Do we need a Section 3 and 4 in this document? If so, do we want to expand on Section 4 in this paragraph, or start a new one just for Section 4?

Although bench and environmental test procedures are not included in the installed system tests, their successful completion is a precondition to completion of the installed tests. In certain instances, however, installed system tests may be used in lieu of bench test simulation of such factors as power supply characteristics, interference from or to other equipment installed on the aircraft, etc. Installed tests are normally performed under two conditions:

- a. with the aircraft on the ground and using simulated or operational system inputs, and/or
- b. with the aircraft in flight using operational system signals appropriate to the equipment under test.

Test results may be used to demonstrate functional performance in the intended operational environment.

In addition, the ground test procedures may be used as an optional check of equipment performance following corrective maintenance.

1.81.5 Definition of Terms

ATCRBS – Air Traffic Control Radar Beacon System.

<u>Desensitization</u> – Temporary reduction of transponder sensitivity after receipt of a signal. Used to reduce echo (multipath) effects.

<u>Interrogation</u> – A ground or airborne signal propagated toward an ATCRBS transponder to elicit a Mode A or Mode C response.

<u>Mode A Interrogation</u> – A signal <u>to elicit</u> an ATCRBS <u>transponder reply for identity</u> (4096 code) <u>and surveillance</u>.

<u>Mode C</u> Interrogation – A signal to <u>elicit</u> an ATCRBS <u>transponder reply for automatic</u> <u>pressure-altitude transmission and surveillance</u>

<u>Multipath</u> – The propagation phenomenon that results in signals reaching the receiving antenna by two or more paths, generally with a time or phase difference between the two.

<u>National Airspace System (NAS)</u> – The common system of facilities, equipment, regulations, procedures and personnel providing services and standard procedures for the safe and efficient movement of civil and military aircraft within the jurisdiction of the United States.

<u>PAM</u> – Pulse <u>Amplitude Modulation</u>. <u>The modulation technique utilized in both the interrogation and reply signals</u>.

Reply – A signal propagated from the transponder.

<u>Side Lobe Suppression (SLS) Transmission</u> – A transmission intended to prevent responses from transponders not in the main beam of the interrogating antenna.

<u>Special Position Identification (SPI)</u> - A special pulse used in ATCRBS located 4.35 microseconds following the last framing pulse. When used in Mode S, SPI appears as a code in the flight status (FS) field and in the surveillance status subfield (SSS).

© 2007, RTCA, Inc. DRAFT V0.4<u>5a</u>

2 <u>ATCRBS TRANSPONDER</u> EQUIPMENT PERFORMANCE REQUIREMENTS AND TEST PROCEDURES

2.1 General Requirements

Minimum Operational Performance Standards of navigation, communication and ATC systems should be established and widely published. Where services provided in these areas depend upon certain characteristics of the airborne elements, minimum requirements must be established to assure that all airborne equipments are compatible with and operate properly within the service being provided. Such minimum requirements should be restricted to the actual minimum operational or performance characteristics and should not contain equipment specifications. These should be the prerogatives of the purchaser or seller of the equipment.

Further, the minimum requirements need not contain environmental standards, although such standards may be found useful and be utilized by manufacturers and purchasers to indicate that a given device can meet its operational characteristics in the intended application. The need is simply for the user to assure that his equipment will meet the needed operational characteristics in the environmental conditions in which he operates. As a means of determining the environmental characteristics of airborne equipment, there should be a convenient grouping of categories of environment encountered in typical aircraft. This type of standard is optional or guidance material, and may be used by equipment manufacturers or users to identify given equipment environmental capability. An equipment manufacturer has the option of:

Using the FAA "Environmental Test Procedures for Airborne Electronic Equipment," set forth in FAA Technical Standard Orders (TSO's); or

Using industry-developed environmental standards (such as RTCA, SAE); or

Stating the range of environmental conditions over which his equipment is capable of operating. As a minimum, temperature and altitude limitations should be stated. In order to achieve some degree of uniformity in the manner in which manufacturers state the range of environmental conditions over which their equipment is capable of operating, it is recommended that the environmental categories defined in the report of RTCA Special Committee 112 be employed for this purpose (See RTCA/DO-138).

2.1.1 Airworthiness

In the design and manufacture of the equipment, the manufacturer shall provide for installation so as not to impair the airworthiness of the aircraft.

2.1.2 <u>Intended Function General Performance</u>

The equipment **shall** perform its intended function(s), as defined by the manufacturer, and its proper use **shall not** create a hazard to other users of the National Airspace System.

2.1.3 Federal Communications Commission Rules

All equipment **shall** comply with the applicable rules of the Federal Communication Commission.

2.1.4 Fire Protection

All materials used **shall** be self-extinguishing except for small parts (such as knobs, fasteners, seals, grommets and small electrical parts) that would not contribute significantly to the propagation of a fire.

<u>Note:</u> One means of showing compliance is contained in Federal Aviation Regulations (FAR), Part 25, Appendix F.

2.1.5 Operation of Controls

The equipment **shall** be designed so that controls intended for use during flight cannot be operated in any position, combination or sequence that would result in a condition detrimental to the reliability of the equipment or operation of the aircraft.

2.1.6 Accessibility of Controls

Controls that do not require adjustment during flight **shall not** be readily accessible to flight personnel.

2.1.7 Flight Crew Control Functions

The following functions shall be provided.

- a. Means of selecting each of the ATCRBS 4096 (Mode A) reply codes, and of indicating the code selected.
- Means of selecting the condition in which all transponder functions, other than transmission on the reply frequency and associated self-testing, are operational (i.e., the Standby condition). Return to normal operation from this condition shall be possible within five seconds
- c. Means of selecting ATCRBS Mode A and Mode C combined.
- d. Means of initiating the IDENT (SPI) feature.
- e. Means of inhibiting the transmission of the altitude information, while retaining the ATCRBS framing pulses in ATCRBS Mode C replies.

2.1.8 Optional Functions/Interfaces

With the movement toward an Automatic Dependent Surveillance – Broadcast (ADS-B) environment, there are various functions/outputs from the ATCRBS transponder that are in common with ADS-B parameter requirements. For example, the "squawk" or 4096 code, pressure altitude, and an IDENT capability are features used by both ADS-B and ATCRBS in supporting ATC surveillance needs. Equipment manufacturers should consider the

development of an output interface to support these and other ADS-B broadcast requirements (e.g. Flight ID) in their future transponder designs.

2.1.9 Effects of Test

The equipment **shall** be designed so that the application of specified test procedures **shall not** be detrimental to equipment performance following the application of the tests, except as specifically allowed. The 4096 codes specified in §2.2.4 **shall** be manually selectable for reply to interrogations on Mode 3/A.

2.1.10 Interrogation Characteristics

The following subsections describe the signal in space as it can be expected to appear at the transponder's antenna. Because signals can be corrupted in transmission, tolerances for interrogator performance are more restrictive and should not be derived from this document. The modulation techniques utilized in the interrogation signal is known as pulse amplitude modulation (PAM).

2.1.10.1 Interrogation Carrier Frequency

The carrier frequency of received interrogations is:

a. 1030 ±0.2 MHz from ATCRBS interrogators.

b. 1030 ±0.01 MHz from Mode S interrogators.

2.1.10.2 Measurement Convention

The following definitions are in reference to Figure 2-1.

<u>Pulse amplitude</u> – the peak voltage amplitude (A) of the pulse envelope.

<u>Pulse rise time</u> – the time between 0.1A and 0.9A on the leading edge of the pulse envelope.

<u>Pulse decay time</u> – the time between 0.9A and 0.1A on the trailing edge of the pulse envelope.

<u>Pulse duration</u> – the time interval between 0.5A points on leading and trailing edges of the pulse envelope.

<u>Pulse interval</u> – the time interval between the 0.5A point on the leading edge of the first pulse and the 0.5A point on the leading edge of the second pulse.

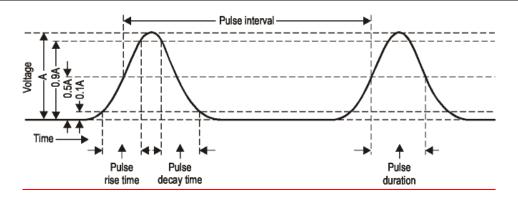


Figure 2-1 Pulse Envelope Conventions

2.1.10.3 Received PAM Signals

The following signals are valid PAM interrogations:

- ATCRBS Mode A (to elicit transponder replies for identity and surveillance)
- ATCRBS Mode C (to elicit transponder replies for automatic pressure-altitude transmission and surveillance)
- ATCRBS Mode A/C/S All-Call (to elicit replies for surveillance of Mode A/C transponders and for the acquisition of Mode S transponders)
- ATCRBS Mode A/C-Only All-Call (to elicit replies for surveillance of Mode A/C transponders. Mode S transponders do not reply)

All of these interrogations use two or more of the four pulses shown in paragraph 2.1.10.3.2. The pulses are labeled P_1 , P_2 , P_3 and P_4 .

2.1.10.3.1 Pulse Shapes

The pulse shapes for PAM interrogations are summarized below (all values are in microseconds).

Pulse	<u>Pulse</u>	Duration	Rise Time	Decay Time
Designator	Duration	Tolerance	Min/Max	Min/Max
<u>P₁, P₂, P₃</u>	0.8	<u>±0.1</u>	0.05/0.1	0.05/0.2
P ₄ (short)	0.8	<u>±0.1</u>	0.05/0.1	0.05/0.2
P ₄ (long)	<u>1.6</u>	<u>±0.1</u>	0.05/0.1	0.05/0.2

2.1.10.3.2 Pulse Patterns

The pulse patterns of the PAM interrogations are defined as follows (all values are in microseconds). The general format of the PAM interrogations is shown in Figure 2-2.

Interrogation Type	Spacing				
	<u>P</u> ₁ – <u>P</u> ₂	<u>P</u> ₁ <u>P</u> ₃	<u>P</u> ₃ – <u>P</u> ₄	<u>P</u> 4	
ATCRBS Mode A	2 ± 0.15	<u>8 ±0.2</u>		None	
ATCRBS Mode C	2 ±0.15	21 ±0.2		None	
ATCRBS Mode A/Mode S All-Call	2 ±0.15	<u>8 ±0.2</u>	2 ±0.05	<u>Long</u>	
ATCRBS Mode C/Mode S All-Call	2 ±0.15	21 ±0.2	2 ±0.05	Long	
ATCRBS Mode A-Only All-Call	<u>2 ±0.15</u>	<u>8 ±0.2</u>	2 ±0.05	Short	
ATCRBS Mode C-Only All-Call	<u>2 ±0.15</u>	21 ±0.2	2 ±0.05	Short	

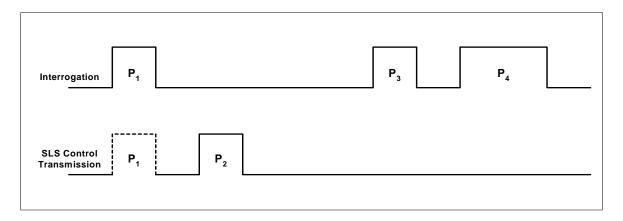


Figure 2-2 General Pulse Patterns for PAM Interrogations

2.1.10.3.3 Relative Pulse Amplitudes

P₂ amplitudes will vary from P₁.

 P_3 amplitudes are $P_1 \pm 1$ dB.

P₄ amplitudes are P₃ ±1 dB.

DRAFT V0.4<u>5a</u> © 2007, RTCA, Inc.

2.1.10.4 Suppression

This characteristic is used to prevent replies to interrogations received via the side lobes of the interrogator antenna, and to prevent Mode A/C transponders from replying to Mode S interrogations. Suppression is in effect when the received amplitude of P_2 is equal to or in excess of the received amplitude of P_1 and spaced 2 ± 0.15 microseconds (see § 2.2.5.3).

2.2 Equipment Performance – Standard Conditions

2.2.1 Definition of Standard Conditions

The signal levels specified in this subsection exist at the antenna end of a transponder-toantenna transmission line of loss equal to the maximum for which the transponder is designed.

<u>Note:</u> The transponder will usually be installed with less than the designed maximum transmission line loss. Nevertheless, the standard conditions of this document are based on the maximum design value.

Comment: When comparing the organization of the requirements in this draft document to the organization of the requirements in DO-181, there is a more logical grouping in DO-181. For example, in DO-181, the section "Receiver Characteristics" includes the requirements for sensitivity and dynamic range (receiver characteristics), whereas in this document, these requirements are under pulse decoder characteristics. SC-209 may want to consider re-organizing the requirements and associated test procedures in this document.

2.2.2 Receiver Characteristics

2.2.2.1 Transponder Receiver Bandwidth

The skirt bandwidth should be such that the sensitivity of the transponder is at least 60 db down at frequencies outside the band 1030 ± 25 MHz. The response to signals with pulse groups and with pulse spacings of 2 microseconds and 8 microseconds in the band 30 to 1500 MHZ, excluding the band 960 to 1215 MHz, **shall** be at least 60 db below maximum sensitivity.

2.2.2.2 **Response to Interrogations**

The equipment shall accept and reply to all valid ATCRBS Mode A and C interrogations as specified in §2.1.10.3.

2.2.3 Transmitter Characteristics

There should be a sub-section heading: "Reply Transmission Frequency" inserted here.

The center frequency of the reply transmission **shall** be 1090 MHz. The frequency tolerance shall be ±3 MHz.

2.2.3.1 Transponder Power Output

2.2.3.1.1 Class A Equipment

<u>Class Aa.</u> For equipment <u>is</u> intended for installation in aircraft which operate at altitudes above 15,000 feet. For this class of equipment, the peak pulse power available at the antenna end of the transmission line of the transponder **shall** be at least 21 db and not more than 27 db above 1 watt.

2.2.3.1.2 Class B Equipment

b. For Class B equipment is intended for installation in aircraft which operate at altitudes not exceeding 15,000 feet. For this class of equipment, the peak pulse power-available at the antenna end of the transmission line of the transponder **shall** be at least 18.5 db and not more than 27 db above 1 watt.

Note: For the power output requirement of specified in §2.2.3.1.1 and §2.2.3.1.2, the above Paragraphs "a" and "b," a nominal 3 db transmission line loss and an antenna performance equivalent to that of a simple quarter-wave antenna are assumed. In the event these assumed conditions do not apply, the peak pulse power of the installed transponder system must be comparable to that of the assumed system.

2.2.3.1 Emission of Spurious RF Energy

With the transponder is operating, but not being interrogated, the level of spurious CW RF energy, as measured at the output terminal of the transponder, over the range 960 to 1215 MHz shall not exceed 70 dbw.

Recommendation: With the transponder operating, but not being interrogated, the level of spurious CW RF energy as measured at the output terminal of the transponder, at all frequencies allocated to the aeronautical service outside of the range 960 to 1215 MHz should not exceed 70 dbw.

2.2.4 Reply Pulse Characteristics (Signals in Space)

<u>The following</u> subsections <u>describe the</u> reply pulse characteristics. The general format of the reply pulse is shown in Figure 2-3.

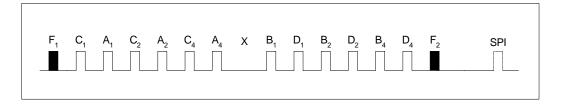


Figure 2-3 ATCRBS Reply Mode Pulse Pattern

2.2.4.1 Framing Pulses

The reply function **shall** employ a signal comprising two framing pulses spaced 20.3 microseconds, as the most elementary code.

2.2.4.2 Information Pulses

Information pulses **shall** be spaced in increments of 1.45 microseconds from the first framing pulse. The designation and position of these information pulses **shall** be as follows:

Position Pulse (microseconds) 0.00 F_1 1.45 C_1 2.90 A_1 4.35 C_2 5.80 A_2 7.25 C_4 8.70 A_4 X 10.15 11.60 B_1 13.05 D_1 14.50 B_2 15.95 D_2 17.40 B_4 18.85 D_4 20.30 F_2

Table 2.2.4.2: Information Pulses

2.2.4.3 Special Position Identification (SPI) Pulses

In addition to the information pulses provided, a Special Position Identification (SPI) Pulse, which may be transmitted with the information pulses, **shall** occur at a pulse interval of 4.35 microseconds following the last framing pulse.

2.2.4.4 Reply Pulse Shape

All reply pulses **shall** have a pulse duration of 0.45 ± 0.10 microsecond, a pulse rise time between 0.05 and 0.1 microsecond, and a pulse decay time between 0.05 and 0.2 microsecond. The pulse amplitude variation of one pulse with respect to any other pulse in a reply group **shall not** exceed 1 db. (See § 2.1.10.2)

Note: The intent of the lower limit of rise and decay times (0.05 microsecond) is to reduce sideband radiation. Equipment will meet this requirement if the sideband radiation is no greater than that which theoretically would be produced by a trapezoidal wave having 0.05 microsecond rise and decay times and a 0.35 microsecond pulse duration.

2.2.4.5 Reply Pulse Interval Tolerances

The pulse interval tolerance for each pulse (including the last framing pulse) with respect to the first framing pulse of the reply group **shall** be ± 0.10 microsecond. The pulse interval tolerance of the Special Position Identification Pulse with respect to the last framing pulse of the reply group **shall** be ± 0.10 microsecond. The pulse interval tolerance of any pulse in the reply group with respect to any other pulse (except the first framing pulse) **shall** not exceed ± 0.15 microsecond.

2.2.4.6 Reply Delay and Jitter

The time delay between the arrival at the transponder of the leading edge of P_3 , and the transmission of the leading edge of the first pulse of the reply **shall** be 3 ± 0.5 microseconds. The total jitter of the reply pulse code group with respect to P_3 **shall not** exceed ± 0.1 microsecond for receiver input levels between 3 and 50 db above minimum triggering level. Delay variations between modes on which the transponder is capable of replying **shall not** exceed 0.2 microseconds.

2.2.4.7 Transmission Time of Special Position Identification (SPI) Pulse

When manually initiated, the SPI pulse **shall** be transmitted for a period of between 15 and 30 seconds and must be capable of being reinitiated at any time.

2.2.5 **Decoding Performance**

2.2.5.1 Reply

This section should include specific requirements for pulse position tolerances. The test procedure associated with this requirements section tests the pulse position tolerances, yet there are no requirements explicitly stated in section 2.2 of this document. The tolerances are currently only implied in the table in section 2.1.10.3.2.

When selected to reply to a particular interrogation mode (See Appendix A§ 2.1.10), the transponder **shall** reply (not less than 90 percent efficiency) under each of the following conditions:

- a. The received amplitude of P_3 is in excess of a level 1 db below the received amplitude of P_1 but no greater than 3 db above the received amplitude of P_1 .
- b. Either the received amplitude of P_1 is in excess of a level of 9 db above the received amplitude of P_2 , or no pulse is received at the position 2 ± 0.7 microseconds. following P_1 .
- c. The received amplitude of a proper interrogation is more than 10 db above the received amplitude of random pulses where the latter are not recognized by the transponder as P_1 , P_2 , or P_3 .

2.2.5.2 No Reply

The transponder **shall not** reply to more than 10 percent of the interrogations under each of the following conditions:

- a. To interrogations when the interval between pulses P_1 and P_3 differs from that defined in § 2.1.10.3.2 for the mode selected in the transponder by more than ± 1 microsecond.
- b. Upon receipt of any single pulse which has no amplitude variations approximating a normal interrogation condition.

2.2.5.3 Suppression

Upon receipt of an interrogation complying with the interrogation modes defined in § 2.1.10.34, selected manually or automatically, the transponder **shall** be suppressed (not less than 99 percent efficiency) when the received amplitude of P_2 is equal to or in excess of the received amplitude of P_1 and spaced 2 ± 0.15 microseconds.

<u>Note:</u> It is not the intent of this paragraph to require the detection of P_3 as a prerequisite for initiation of suppression action.

- a. The transponder suppression **shall** be for a period of 35 \pm 10 microseconds.
- b. The suppression **shall** be capable of being reinitiated for the full duration within two microseconds after the end of any suppression period.

c. The transponder **shall not** initiate suppression after reception of a valid interrogation.

Note:. After reception of a valid interrogation as specified in § 2.2.5.1, the transponder should be in "dead time" (see §2.2.7.1) to prevent initiation of suppression based on reception of a subsequent P_4 pulse.

2.2.6 Pulse Decoder Characteristics

2.2.6.1 Receiver Sensitivity and Dynamic Range

- a. The minimum triggering level (MTL) of the transponder **shall** be such that replies are generated to 90 percent of the interrogation signals when:
 - (1) The two pulses P₁ and P₃ constituting an interrogation are of equal amplitude and P₂ is not detected; and
 - (2) The amplitude of these signals received at the antenna end of the transmission line of the transponder is nominally 71 db below 1 milliwatt with limits between 69 and 77 db below 1 milliwatt.

Note: For this MTL requirement, a nominal 3 db transmission line loss and an antenna performance equivalent to that of a simple quarter wave antenna are assumed. In the event these assumed conditions do not apply, the MTL of

the installed transponder system must be comparable to that of the assumed system.

- b. The variation of the minimum triggering level between modes **shall not** exceed 1 db for nominal pulse spacings and pulse widths.
- c. The reply characteristics **shall** apply over a received signal amplitude range between minimum triggering level and 50 db above minimum triggering level.
- d. The suppression characteristics **shall** apply over a received, signal amplitude range between 3 db above minimum triggering level and 50 db above minimum triggering level.

2.2.6.2 Pulse Duration Discrimination

- a. Signals of received amplitude between minimum triggering level and 6 db above this level, and of a duration less than 0.3 microsecond at the antenna, **shall not** cause the transponder to initiate more than 10% reply or suppression action.
- b. With the exception of single pulses with amplitude variations approximating an interrogation, any single pulse of a duration more than 1.5 microseconds **shall not** cause the transponder to initiate reply or suppression action over the signal amplitude range of minimum triggering level to 50 db above minimum triggering level.

2.2.7 Desensitization and Recovery Characteristics

2.2.7.1 Dead Time

- a. After reception of a proper valid interrogation as specified in § 2.2.5.1, the transponder **shall not** reply to any other interrogation at least for the duration of the reply pulse train. This dead time **shall** end no later than 125 microseconds after the transmission of the last reply pulse of the group.
- b. The dead time of the transponder created by means other than normal interrogations **shall not** exceed a period of more than 2500 microseconds duration at a maximum duty cycle of 4.5 percent.

2.2.7.2 Echo Suppression and Recovery

The transponder **shall** contain an echo suppression facility designed to permit normal operation in the presence of echoes of signals-in-space. The provision of this facility **shall** be compatible with the requirements for suppression of side lobes given in §2.2.5.3.

2.2.7.2.1 Desensitization

Upon receipt of any pulse more than 0.7 microseconds in duration, the receiver **shall** be desensitized by an amount that is within at least 9 db of the amplitude of the desensitizing pulse, but **shall** at no time exceed the amplitude of the desensitizing pulse, with the exception of possible overshoot during the first microsecond following the desensitizing pulse. Single pulses of duration less than 0.7 microseconds are not required to cause the specified desensitization, and **shall not** cause desensitization of duration greater than that permitted herein or by §2.2.7.2.2.

2.2.7.2.2 Recovery

Following desensitization, the receiver **shall** recover sensitivity (within 3 db of minimum triggering level) within 15 microseconds after reception of a desensitizing pulse having a signal strength up to 50 db above minimum triggering level. Recovery **shall** be nominally linear at an average rate not exceeding 3.5 db per microsecond.[ICAO Annex 10 says 4.0dB]

<u>Note:</u> Transponders that respond to military modes will recover within 15 microseconds, but may employ methods other than nominally linear recovery.

The following section (2.2.7.3) belongs in 2.2.7.4 c and should be moved.

2.2.7.3 Sensitivity Reduction Reply Rate Control

A sensitivity reduction type reply rate limit control **shall** be incorporated in the transponder. The range of this control **shall** permit adjustment, as a minimum, to any value between 500 and 2,000 replies per second, or to the maximum reply rate capability, if less than 2,000 replies per second, without regard to the number of pulses in each reply. Sensitivity reduction in excess of 3 db **shall not** take effect until 90 percent of the selected value is exceeded. Sensitivity reduction **shall** be at least 30 db for rates in excess of 150 percent of the selected value.

Note: The reply rate limit control should be set at 1,200 replies per second, or the maximum value below 1,200 replies per second of which the transponder is capable. (See §2.2.7.4.b, below).

2.2.7.32.2.7.4 Reply Rate

- a. For <u>Class A equipment equipment</u> (see § 2.2.3.1.1)intended for installation in aircraft which operate at altitudes above 15,000 feet, the transponder **shall** be capable of at least 1,200 replies per second for a 15-pulse coded reply.
- b. For <u>Class B</u> -equipment (see § 2.2.3.1.2), intended for installation in aircraft which operate at altitudes not exceeding 15,000 feet, the transponder **shall** be capable of at least 1,000 replies per second for a 15-pulse coded reply.
- c. A sensitivity reduction type reply rate limit control shall be incorporated in the transponder. The range of this control shall permit adjustment, as a minimum, to any value between 500 and 2,000 replies per second, or to the maximum reply rate capability, if less than 2,000 replies per second, without regard to the number of pulses in each reply. Sensitivity reduction in excess of 3 db shall not take effect until 90 percent of the selected value is exceeded. Sensitivity reduction shall be at least 30 db for rates in excess of 150 percent of the selected value.

Recommendation: The reply rate limit control should be set at 1,200 replies per second, or the maximum value below 1,200 replies per second of which the transponder is capable. (See Paragraph b, above).

2.2.8 Undesired Replies

2.2.8.1 Random Triggering and Suppression Rate

In the absence of valid interrogation signals, the random triggering rate (squitter) of the transponder **shall not** exceed 30–30_replies and/or suppressions per second as integrated over an interval equivalent to at least 300 random triggers, or 30 seconds, whichever is less.

Note: When demonstrating compliance to the requirements of § 2.2.8.1, the equipment manufacturer should consider possible interference (triggering) caused by equipment typically found in the aircraft of intended installation (e.g., VHF communication, DME, Radio Altimeter, etc.), operating at their maximum interference levels.

2.2.8.2 **Spurious Responses**

All spurious responses, including response to image frequencies, **shall** be such that the sensitivityresponse to such signals is at least 60 db down from the normal sensitivity of the receiver.

2.2.102.2.9 Transponder Self Test and Monitor

2.2.10.12.2.9.1 Manual Self-Test

- <u>a.</u> (1)—When a manual self-test device is provided, it **shall** be limited to intermittent use by a spring-loaded return-to-off switch, or equivalent.
- <u>b.</u> (2) The test interrogation rate **shall not** exceed 450 per second.
- c. (3)—The lowest RF level at the input to the antenna required to accomplish the test **shall** be used. The maximum RF level at the input to the antenna **shall not** exceed 40 db below 1 milliwatt.

2.2.10.22.2.9.2 Automatic Self-Test

- <u>a.</u> (1) When an automatic self-test device is provided, it **shall** be limited to use only in the absence of a valid ground-interrogation. (A minimum period of 15 seconds will be sufficient to establish the absence of ground interrogations).
- <u>b.</u> (2)—The maximum test time for the automatic self-test **shall not** exceed 0.1 second in any given 15-second interval.
- c. (3) The test interrogation rate **shall not** exceed 450 per second.
- d. (4) The lowest RF level at the input to the antenna required to accomplish the test **shall** be used. The maximum RF level at the input to the antenna **shall not** exceed 40 db below 1 milliwatt.

2.2.112.2.10 Response in-to Mutual Suppression Pulses

If the equipment is designed to accept and respond to suppression pulses from other electronic equipment in the aircraft (to disable it while the other equipment is

transmitting), the equipment must regain normal sensitivity within 3 db, not later than 15 microseconds after the end of the applied suppression pulse.

2.2.132.2.11 Data Handling and Interfaces

2.2.13.12.2.11.1 Code Nomenclature

The code designations **shall** consist of four digits, each of which lies between 0 and 7 inclusive, and is determined by the sum of the pulse subscripts given in Table 2.2.4.2, employed as shown in Table 2.2.4311.1 below:

 Digit
 Pulse Group

 First (most significant)
 A

 Second
 B

 Third
 C

 Fourth
 D

Table 2.2.1311.1: Code Nomenclature

Examples:

Code 3615 would consist of information pulses A1, A2 (1 + 2 = 3), B2, B4 (2 + 4 = 6), C1 (1 = 1), D1, D4 (1 + 4 = 5).

Code 3600 would consist of information pulses A₁, A₂, B₂ and B₄

Code 2057 would consist of information pulses A₂, C₁, C₄, D₁, D₂ and D₄

Code 0301 would consist of information pulses B₁, B₂ and D₁

2.2.13.22.2.11.2 Identification

The 4096 codes specified in § 2.2.11.1 shall be manually selectable for reply to interrogations on Mode A.

2,2,13,32,2,11.3 Pressure Altitude Transmissions

- <u>a.</u> (1)—Independently of the other modes and codes manually selected, the transponder **shall** automatically reply to Mode C interrogations.
- <u>b.</u> (2) The reply to Mode C interrogations **shall** consist of the two framing pulses together with the information pulses specified in § 2.2.4.2.
- c. (3) At as early a date as practicable, <u>The</u> transponders shall be provided with means to remove the information pulses, but to retain the framing pulses when the provision of §2.2.<u>1311</u>.3.(<u>6f</u>) is not complied with, in reply to Mode C interrogation.

<u>Note:</u> The information pulses should be capable of being removed either in response to a failure detection system or manually at the request of the controlling agency.

- d. (4)—The information pulses **shall** be automatically selected by an analog-to-digital converter connected to a pressure-altitude data source in the aircraft referenced to the standard pressure setting of 29.92 inches of mercury.
- e. (5)—Pressure altitude **shall** be reported in 100-foot increments by selection of pulses as shown in the tables in Appendix A. If the transponder is capable of accepting altitude sources with 25-foot or better resolution, the pressure altitude-information **shall** be reported in the closest 100-foot increment as specified in Appendix A.
- <u>f.</u> (6)—The digitizer code selected **shall** correspond to within ± 125 feet, on a 95 percent probability basis with the pressure altitude information (referenced to the standard pressure setting of 29.92 inches of mercury) used on board the aircraft to adhere to the assigned flight profile.

2.2.142.2.12 ATCRBS Transponder Emission of Spurious RF Energy

With the transponder operating, but not being interrogated, the level of spurious CW RF energy, as measured at the output terminal of the transponder, over the range 960 to 1215 MHz **shall not** exceed -70 dbw.

2.2.152.2.13 Antenna

2.2.15.12.2.13.1 Frequency

The antenna **shall** be designed to receive and transmit vertically polarized signals in the frequency range of 1030 to 1090 MHz.

2.2.15.22.2.13.2 Impedance and VSWR

The VSWR produced by the antenna when terminated in a 50-ohm transmission line **shall** not exceed 1.5:1 over the 1030 to 1090 MHz frequency band.

2.2.15.32.2.13.3 Polarization

The antenna **shall** be vertically polarized.

2.2.15.42.2.13.4 Radiation Pattern

The transponder antenna system when installed on an aircraft **shall** have a radiation pattern that is essentially omni-directional in the horizontal plane and should have a vertical beam-width sufficient to provide system operation during normal maneuvers of the aircraft.

2.2.162.2.14 Power Interruption

The transponder equipment **shall** regain operational capability to within its operational limits within two seconds after the restoration of power following a momentary power interruption.

Note: The transponder equipment is not required to continue operation during momentary power interruptions.

© 2007, RTCA, Inc. DRAFT V0.4<u>5a</u>

2.3 Equipment Performance – Environmental Conditions

The environmental tests and performance requirements described in this subsection are intended to provide a laboratory means of determining the overall performance characteristics of the equipment under conditions representative of those that may be encountered in actual aeronautical operation.

Unless otherwise specified, the test procedures applicable to a determination of equipment performance under environmental test conditions are contained in RTCA Document No. DO-160E, *Environmental Conditions and Test Procedures for Airborne Equipment*. General information on the use of RTCA/DO-160E is contained in Sections 1 through 3 of that document. Also, a method of identifying which environmental tests were conducted and other amplifying information on the conduct of the tests is contained in Appendix A of RTCA/DO-160E.

Some of the performance requirements in Subsection 2.2 are not required to be tested to all of the conditions contained in RTCA/DO-160E. Judgement and experience have indicated that these particular parameters are not susceptible to certain environmental conditions and that the level of performance specified in Subsection 2.2 will not be measurably degraded by exposure to these conditions.

In addition to the exceptions above, certain environmental tests contained in this subsection are not required for minimum performance equipment unless the manufacturer wishes to qualify the equipment for additional environmental conditions. If the manufacturer wishes to qualify the equipment to these additional conditions, then these tests shall be performed.

2.3.1 Temperature and Altitude Tests (RTCA/DO-160E, Section 4.0)

RTCA/DO-160E contains several temperature and altitude test procedures that are specified according to equipment category. These categories are included in §4.3 of RTCA/DO-160E. The following subparagraphs contain the applicable test conditions specified in Section 4.0 of RTCA/DO-160E.

2.3.1.1 Low Operating Temperature Test

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §4.5.2, and the following requirements of this standard **shall** be met;

2.3.1.2 High Short-Time Operating Temperature Test

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §4.5.3, and the following requirements of this standard **shall** be met:

2.3.1.3 High Operating Temperature

The equipment **shall** be subject to the test conditions as specified in RTCA/DO-160E, §4.5.4, and the following requirements of this standard **shall** be met:

2.3.1.4 In-Flight Loss of Cooling

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §4.5.5, and the following requirements of this standard **shall** be met:

2.3.1.5 Altitude Tests

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §4.6.1, and the following requirements of this standard **shall** be met:

2.3.1.6 Decompression Test

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §4.6.2, and the following requirements of this standard **shall** be met:

2.3.1.7 Overpressure Test

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §4.6.3, and the following requirements of this standard **shall** be met:

2.3.2 Temperature Variation Test (RTCA/DO-160E, Section 5.0)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §5.0, and the following requirements of this standard **shall** be met:

2.3.3 Humidity Test (RTCA/DO-160E, Section 6.0)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §6.0, and the following requirements of this standard **shall** be met:

2.3.4 Shock Tests (RTCA/DO-160E, Section 7.0)

2.3.4.1 Operational Shocks

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §7.2, and the following requirements of this standard **shall** be met:

2.3.4.2 Crash Safety Shocks

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §7.3, and **shall** meet the requirements specified therein.

The application of the Crash Safety Shock tests may result in damage to the equipment under test. Therefore this test may be conducted after the other tests have been completed. In this case, §2.1.7, "Effects of Test" does not apply.

2.3.5 Vibration Tests (RTCA/DO-160E, Section 8.0)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §8.0, and the following requirements of this standard **shall** be met:

2.3.6 Explosion Test (RTCA/DO-160E, Section 9.0)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §9.0. During these tests, the equipment **shall not** cause detonation of the explosive mixture within the test chamber.

2.3.7 Waterproofness Test (RTCA/DO-160E, Section 10.0)

2.3.7.1 Drip Proof Test

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §10.3.2, and the following requirements of this standard **shall** be met:

2.3.7.2 Spray Proof Test

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §10.3.3, and the following requirements of this standard **shall** be met:

This test **shall** be conducted with the spray directed perpendicular to the equipment.

2.3.7.3 Continuous Stream Proof Test

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §10.3.4, and the following requirements of this standard **shall** be met:

This test **shall** be conducted with the spray directed perpendicular to the equipment.

2.3.8 Fluids Susceptibility Tests (RTCA/DO-160E, Section 11.0)

The following subparagraphs contain the applicable test conditions specified in §11.0 of RTCA/DO-160E.

2.3.8.1 Spray Test

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §11.4.1, and the following requirements of this standard **shall** be met:

- a. At the end of the 24-hour operational period, the equipment **shall** function.
- b. Following the two-hour operational period at ambient temperature, after the 160 hour exposure period at elevated temperature, the following requirements of this standard **shall** be met:

2.3.8.2 Immersion Test

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §11.4.2, and the following requirements of this standard **shall** be met:

- e.a. At the end of the 24-hour operational period, the equipment **shall** function.
- <u>d.b.</u> Following the two-hour operational period at ambient temperature, after the 160 hour exposure period at elevated temperature, the following requirements of this standard **shall** be met:

2.3.9 Sand and Dust Test (RTCA/DO-160E, Section 12.0)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §12.0, and the following requirements of this standard **shall** be met:

2.3.10 Fungus Resistance Test (RTCA/DO-160E, Section 13.0)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §13.0, and the following requirements of this standard **shall** be met:

2.3.11 Salt Spray Test (RTCA/DO-160E, Section 14.0)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §14.0, and the following requirements of this standard **shall** be met:

2.3.12 Magnetic Effect Test (RTCA/DO-160E, Section 15.0)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §15.0, and the equipment **shall** meet the requirements of the appropriate instrument or equipment class specified therein.

2.3.13 Power Input Tests (RTCA/DO-160E, Section 16.0)

2.3.13.1 Normal Operating Conditions

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §16.5.1, as appropriate, and the following requirements of this standard **shall** be met:

2.3.13.2 Abnormal Operating Conditions

The application of the Low Voltage Conditions (DC) (Category B Equipment) test may result in damage to the equipment under test. Therefore, this test may be conducted after the other tests have been completed. §2.1.7 "Effect of Test" does not apply,

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §16.5.2, as appropriate, and the following requirements of this standard **shall** be met:

2.3.14 Voltage Spike Conducted Test (RTCA/DO-160E, Section 17.0)

The following subparagraphs contain the applicable test conditions specified in §17.0 of RTCA/DO-160E.

2.3.14.1 Category A Requirements (If Applicable)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §17.4, and the following requirements of this standard **shall** be met:

2.3.14.2 Category B Requirements (If Applicable)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §17.4, and the following requirements of this standard **shall** be met:

2.3.15 Audio Frequency Conducted Susceptibility Test (RTCA/DO-160E, Section 18.0)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §18.0, and the following requirements of this standard **shall** be met:

2.3.16 Induced Signal Susceptibility Test (RTCA/DO-160E, Section 19.0)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §19.0, and the following requirements of this standard **shall** be met:

2.3.17 Radio Frequency Susceptibility Test (RTCA/DO-160E, Section 20.0)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §20.0, and the following requirements of this standard **shall** be met:

2.3.18 Emission of Radio Frequency Energy Test (RTCA/DO-160E, Section 21.0)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §21.0, and the following requirements of this standard **shall** be met:

2.3.19 Lightning Induced Transient Susceptibility Test (RTCA/DO-160E, Section 22.0)

The equipment **shall** be subjected to the test conditions as specified in RTCA/DO-160E, §22.0, and the following requirements of this standard **shall** be met:

2.4 Equipment Test Procedures

Compliance with the Minimum Operational Performance Standards contained in Section §2.2 may be demonstrated by a combination of bench tests of the individual system components (or certification thereof by either the manufacturer or the installer) and flight tests of the entire installed system. A suggested procedure which will minimize the need for extensive evaluation in the field is as follows in the paragraphs below.

Note: There are multiple references to an appendix A in this document but there is currently no appendix

2.4.1 Definitions of Terms and Conditions of Test (§2.2.1)

The following are definitions of terms and the conditions under which the tests described in this subsection should be conducted.

<u>+)a.</u> Power Input Voltage – Unless otherwise specified, all tests shall be conducted with the power input voltage adjusted to design voltage, plus or minus 2%. The input voltage **shall** be measured at the input terminals of the equipment under test.

2)b. Power Input Frequency

- 1) In the case of equipment designed for operation florm an AC source of essentially constant frequency (e.g., 400 Hz), the input frequency **shall** be adjusted to design frequency, plus or minus 2%.
- 2) In the case of equipment designed for operation form an AC source of variable frequency (e.g., 300 to 1,000 Hz), unless otherwise specified, tests **shall** be conducted with the input frequency adjusted to within 5% of a selected frequency and within the range for which the equipment is designed.
- <u>3)c.</u> Adjustment of Equipment The circuits of the equipment under test **shall** be properly aligned and otherwise adjusted in accordance with the manufacturer's recommended practices prior to application of the specified tests.
- <u>4)d.</u> Test Equipment All equipment used in the performance of the tests should be identified by make, model and serial number where appropriate, and its latest calibration date. When appropriate, all test equipment calibration standards should be traceable to national and/or international standards.
- 5)e. Test Instrument Precautions Adequate precautions shall be taken during the test to prevent the introduction of errors resulting from the connection of voltmeters, oscilloscopes and other test instruments across the input and output impedances of the equipment under test.
- <u>6)f.</u> Ambient Conditions Unless otherwise specified, all tests **shall** be made within the following ambient conditions:

- 1) Temperature: +15 to +35 degrees C (+59 to +95 degrees F).
- 2) Relative Humidity: Not greater than 85%.
- 3) Ambient Pressure: 84 to 1-7 kPa (equivalent to +5,000 to -1,500 ft) (+1,525 to -460m).

<u>7)g.</u>Connected Loads – Unless otherwise specified, all tests **shall** be performed with the equipment connected to loads having the impedance values for which it is designed.

2.4.2 Verification of Receiver Characteristics (§02.2.2)

2.4.2.1 Verification of Transponder Receiver Bandwidth (§2.2.2.1)

Purpose/Introduction:

The skirt bandwidth should be such that the sensitivity of the transponder is at least 60 db down at frequencies outside the band 1030 ± 25 MHz. The response to signals with pulse groups and with pulse spacings of 2 microseconds and 8 microseconds in the band 30 to 1500 MHZ, excluding the band 960 to 1215 MHz, **shall** be at least 60 db below maximum sensitivity.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.17: Interrogate the transponder at 500 interrogations per second with a Mode 3/A interrogation signal. Determine the interrogation signal level (MTL) which results in a transponder reply rate of 450. Set the interrogation frequency to 1055 and 1005 MHz and verify that the transponder sensitivity is at least 60 db below the MTL level measured above in both cases.

2.4.2.4

There is currently no test procedure associated with the "2.2.2.2 Response to Interrogations" that verifies that the transponder replies to the required interrogation formats that include the standard Mode A and Mode C formats with wide or narrow P4 pulse. SC-209 needs to decide to what extent the acceptance of interrogations with a P4 pulse need to be tested. The test could range from a simple verification of acceptance to a more comprehensive test where the current test procedures in sections 2.4.5.1 (2.4.5.2?) and 2.4.6.1 could be modified to include interrogations with the P4 pulse.

2.4.3 Verification of Transmitter Characteristics (§2.2.3)

The center frequency of the reply transmission **shall** be 1090 MHz. The frequency tolerance **shall** be ± 3 MHz.

Define a test procedure.

2.4.3.1 Verification of Transponder Power Output (§2.2.3.1)

Purpose/Introduction:

- a. For equipment intended for installation in aircraft which operate at altitudes above 15,000 feet, the peak pulse power available at the antenna end of the transmission line of the transponder **shall** be at least 21 db and not more than 27 db above 1 watt.
- b. For equipment intended for installation in aircraft which operate at altitudes not exceeding 15,000 feet, the peak pulse power-available at the antenna end of the transmission line of the transponder **shall** be at least 18.5 db and not more than 27 db above 1 watt.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.14: Transponder power output may be determined with a dummy load and power meter which are suitable for use at 1090 MHz.

- (1) For equipment intended for installation in aircraft which operate at altitudes above 15,000 feet, the peak pulse power at the load should be at least +21 dbw and not more than +27 dbw.
- (2) For equipment intended for installation in aircraft which operate at altitudes not exceeding 15,000 feet, the peak pulse power at the load should be at least +18.5dbw and not more than + 27 dbw.

In keeping with the precedent of aligning the order of test procedures with the requirements, the "Verification of Emission of Spurious RF Energy" test should be moved to 2.4.12 and reference 2.2.12.

2.4.3.2 Verification of Emission of Spurious RF Energy (§1.1.1.101.1.1.1.1)

Purpose/Introduction:

With the transponder is operating, but not being interrogated, the level of spurious CW RF energy, as measured at the output terminal of the transponder, over the range 960 to 1215 MHz **shall not** exceed -70 dbw.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.19: With the transponder operating but not being interrogated and with suitable test equipment connected to the transponder output terminal, scan the band of frequencies from 960 to 1215 MHz. Determine that spurious CW signals do not exceed -70 dbw.

<u>Note:</u> In connection with the recommendation contained in §2.2.3.2, see appropriate FCC Rules and Regulations for tables of frequencies allocated to the aeronautical service.

2.4.4 Verification of Reply Pulse Characteristics (Signals in Space) (§2.2.4)

The reply transmission characteristics can be determined with a demodulating probe and a wide band oscilloscope comparing the reply pulse group waveform against an accurate timing waveform such as from a crystal oscillator.

2.4.4.1 Verification of Framing Pulses (§2.2.4.1 and §2.2.4.52.2.4.5)

Purpose/Introduction:

The reply function **shall** employ a signal comprising two framing pulses spaced 20.3 microseconds, as the most elementary code.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.3: With the transponder interrogated on Mode 3/A and replying on Code 0000, the time interval between the 0.5 amplitude points on the leading edges of the two framing pulses should be within 20.3 ± 0.10 microseconds.

2.4.4.2 Verification of Information Pulses (§2.2.4.2 and §2.2.4.5)

Purpose/Introduction:

Information pulses **shall** be spaced in increments of 1.45 microseconds from the first framing pulse. The designation and position of these information pulses **shall** be as shown in Table 2.2.4.2.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.3: With the transponder replying on Code 7777, the time interval between the 0.5 amplitude points on the leading edge of each pulse, including the last framing pulse, with respect to the first framing pulse should be equal to that listed in §2.2.4.2 with a tolerance of ± 10 microsecond. Also, the time interval between any pulse in the reply group with respect to any other pulse (except the first framing pulse) should not exceed ± 0.15 microsecond.

2.4.4.3 Verification of Special Position Identification (SPI) Pulses (§2.2.4.3 and §2.2.4.5)

Purpose/Introduction:

In addition to the information pulses provided, a Special Position Identification Pulse, which may be transmitted with the information pulses, **shall** occur at a pulse interval of 4.35 microseconds following the last framing pulse.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.3: With the transponder replying with the SPI pulse, the time interval between the 0.5 amplitude points on the leading edge of the second framing pulse and the SPI pulse should be 4.35 ± 0.10 microseconds.

2.4.4.4 Verification of Reply Pulse Shape (§2.2.4.4)

Purpose/Introduction:

All reply pulses **shall** have a pulse duration of 0.45 ± 0.10 microsecond, a pulse rise time between 0.05 and 0.1 microsecond, and a pulse decay time between 0.05 and 0.2 microsecond. The pulse amplitude variation of one pulse with respect to any other pulse in a reply group **shall not** exceed 1 db.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.3: With the transponder replying on Code 7777 and the SPI pulse activated, verify the following reply pulse characteristics:

The duration of each reply pulse, as measured between the 0.5 amplitude points on the leading and trailing edge, should be between 0.35 and 0.55 microsecond.

The rise time of each reply pulse, as measured between the 0.1 amplitude and 0.9 amplitude points on the leading edge should be between 0.05 and 0.10 microsecond.

The decay time of each reply pulse, as measured between the 0.9 amplitude and 0.1 amplitude points on the trailing edge should be between 0.05 and 0.20 microsecond.

The amplitude variation of anyone pulse as measured with respect to any other pulse in a reply group should not exceed 1 db.

Note: The fundamental requirements of sideband radiation can be met either as described above or by determining that the actual sideband radiation is no greater than that which theoretically would be produced by a trapezoidal wave having 0.05 microsecond rise and decay times and a 0.35 microsecond pulse duration.

Test procedure 2.4.4.5 is not required since the pulse interval tolerances are verified in the above pulse position measurement procedures. Note: This removal will disrupt the direct test procedure to requirement mapping unless it is filled with a "not used".

2.4.4.5 Verification of Reply Pulse Interval Tolerances (§2.2.4.5)

Purpose/Introduction:

The pulse interval tolerance for each pulse (including the last framing pulse) with respect to the first framing pulse of the reply group **shall** be ± 0.10 microsecond. The pulse interval tolerance of the Special Position Identification Pulse with respect to the last framing pulse of the reply group **shall** be ± 0.10 microsecond. The pulse interval

tolerance of any pulse in the reply group with respect to any other pulse (except the first framing pulse) **shall not** exceed ± 0.15 microsecond.

Measurement Procedures:

Step 1: Brief descriptive title for this test step

2.4.4.6 Verification of Reply Delay and Jitter (§2.2.4.6)

Purpose/Introduction:

The time delay between the arrival at the transponder of the leading edge of P_3 , and the transmission of the leading edge of the first pulse of the reply **shall** be 3 ± 0.5 microseconds. The total jitter of the reply pulse code group with respect to P_3 **shall not** exceed ± 0.1 microsecond for receiver input levels between 3 and 50 db above minimum triggering level. Delay variations between modes on which the transponder is capable of replying **shall not** exceed 0.2 microseconds.

Measurement Procedures:

- (a) Interrogate the transponder with a Mode 3/A signal. Measure the time interval between the 50% voltage point of the leading edge of P_3 and the 50% voltage point of the leading edge of the first framing pulse at the antenna terminal. Vary the interrogation RF level from 3 to 50 db above MTL. The delay should be within the limits of 3 ± 0.5 microsecond.
- (b) Repeat step (a) for Mode C. Verify that the delay variation between Mode A and C does not exceed 0.2 microsecond.
- (c) Measure the jitter from the leading edge of P_3 to the leading edge of the first framing pulse for signal levels between 3 and 50 db above MTL. Perform this test for both Modes A and C. The jitter should not exceed ± 0.1 microsecond.

2.4.4.7 Verification of Transmission Time of Special Position Identification (SPI) Pulse (§2.2.4.7)

Purpose/Introduction:

When manually initiated, the SPI pulse **shall** be transmitted for a period of between 15 and 30 seconds and must be capable of being reinitiated at any time.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.16: Interrogate the transponder with a Mode 3/A interrogation signal. With the transponder operating, manually initiate the SPI pulse and verify that the transmission time of the SPI pulse is between 15 and 30 seconds, and that it can be re-initiated immediately.

DRAFT V0.4<u>5a</u> © 2007, RTCA, Inc.

Change the 2.4.5 section title to "Decoding Performance" to be consistent with the requirements section.

2.4.5 Verification of Side Lobe Characteristics (§Error! Reference source not found.)

2.4.5.1 Verification of Reply (§2.2.5.1)

Purpose/Introduction:

When selected to reply to a particular interrogation mode (See Appendix A), the transponder **shall** reply (not less than 90 percent efficiency) under each of the following conditions:

- a. The received amplitude of P_3 is in excess of a level 1 db below the received amplitude of P_1 but no greater than 3 db above the received amplitude of P_1 .
- b. Either the received amplitude of P_1 is in excess of a level of 9 db above the received amplitude of P_2 , or no pulse is received at the position 2 ± 0.7 microseconds. following P_1 .
- c. The received amplitude of a proper interrogation is more than 10 db above the received amplitude of random pulses where the latter are not recognized by the transponder as P₁, P₂, or P₃.

Measurement Procedures:

Requirements need to be added to section 2.2 defining the pulse position tolerances that are tested in the following test procedure.

Should this test also use interrogations that include the P4 pulse?

Originally from DO-144 §2.3.2.1.4: Interrogate the transponder with interrogation pulse signals described in Appendix A for Mode 3/A and C, at a repetition rate of 500 interrogations per second and with a signal level 3 db above the receiver minimum triggering level (See §2.4.6.1). In the absence of P₂ pulses, slowly adjust the interval between P₁ and P₃ from 7.8 microseconds to 8.2 microseconds, and from 20.8 microseconds to 21.2 microseconds, respectively, and note the reply rate in each case.

- Using the nominal pulse interval between P_1 and P_3 for Mode 3/A, vary the amplitude of P_3 between 1 db below and 3 db above the amplitude of P_1 . Note the lowest reply rate obtained. Repeat for Mode C.
- Increase the signal level of P₁ and P₃ 20 db, (for Mode 3/A only) with P₃ equal in amplitude to P₁ and with P₂ set to an amplitude 9 db below that of P₁ and P₃. Vary the interval of P₂ from 1.3 to 2.7 microseconds with respect to P₁ and note the lowest reply rate obtained.

Verify that the P2 position used in step 3 is in the "must reject" range. The requirement for this is in 2.2.5.1 b. and it indicates that the must reject range is 2 ± 0.7 that puts this test procedure right at the edge of the must reject position.

- (3) Repeat step (2) with the level of P₁, P₂, and P₃ set to be equal. Set the spacing of P₂ at 1.3 and 2.7 microseconds respectively with respect to P₁ and note the reply rate obtained.
- (4) Repeat step (2) above but with P2 at the nominal interval following P1. Combine the interrogation signal with a non-synchronous single pulse generator operating at 5000 prf and at an RF level 10 db below that of P1 and P3.

The reply rates obtained in each case above should be at least 450 replies per second.

2.4.5.2 Verification of No Reply (§2.2.5.2)

<u>Purpose/Introduction:</u>

The transponder **shall** not reply to more than 10 percent of the interrogations under each of the following conditions:

- a. To interrogations when the interval between pulses P_1 and P_3 differs from that defined in Appendix A for the mode selected in the transponder by more than ± 1 microsecond.
- b. Upon receipt of any single pulse which has no amplitude variations approximating a normal interrogation condition.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.5: Interrogate the transponder with interrogation pulse signals described in Appendix A for Modes 3/A and C, at a repetition rate of 500 interrogations per second and with a signal level 3 db above the receiver minimum triggering level. (See §2.3.2.1.8). In the absence of P₂ pulses, adjust the interval between P₁ and P₃ to 7.0, 9.0, 20.0 and 22.0 microseconds, respectively. Note the reply rate in each case. The reply rate should be no more than 50 replies per second.

2.4.5.3 Verification of Suppression (§2.2.5.3)

<u>Purpose/Introduction:</u>

Upon receipt of an interrogation complying with the interrogation modes defined in Appendix A selected manually or automatically, the transponder **shall** be suppressed (not less than 99 percent efficiency) when the received amplitude of P_2 is equal to or in excess of the received amplitude of P_1 and spaced 2 ± 0.15 microseconds.

Note: It is not the intent of this paragraph to require the detection of P_3 as a prerequisite for initiation of suppression action.

- a. The transponder suppression **shall** be for a period of 35 ± 10 microseconds.
- b. The suppression **shall** be capable of being reinitiated for the full duration within two microseconds after the end of any suppression period.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.7: Interrogate the transponder with Mode 3/A interrogation pulse signals described in Appendix A at a repetition rate of 500 interrogations per second and at a signal level of 3 db above receiver minimum triggering level. Adjust P_2 equal in amplitude to P_1 with spacings from 1.85 to 2.15 microseconds and note the reply rate. Repeat with P_2 adjusted to 10 db greater than P_1 and note the reply rate. Both rates should be no greater than 5 replies per second.

- Olisable P₃ and readjust P₂ equal in amplitude to P₁ and at nominal spacing. Using a second signal source (set to at least 3 db above the receiver minimum triggering level) with the interrogation rate synchronized with the first but delayed more than 50 microseconds, interrogate the transponder on Mode 3/A. Gradually shorten the delay until no replies are received from the second interrogation source. Note the interval between P₂ of the first signal source and P₁ of the second signal source. This interval should be between 25 and 45 microseconds.
- (2) Increase the delay time of the second interrogation source by 2 microseconds from that at which no replies were received in step (1) above. There should be at least 450 replies per second from the second interrogation source. Insert a P₂ into the second interrogation source equal in amplitude to P₁. The reply rate from the second interrogation source should not exceed 5 replies per second.

2.4.6 Verification of Pulse Decoder Characteristics (§2.2.6)

2.4.6.1 Verification of Receiver Sensitivity and Dynamic Range (§2.2.6.1)

These tests should include interrogations with P4 pulses (?)

Purpose/Introduction:

- a. The minimum triggering level (MTL) of the transponder shall be such that replies are generated to 90 percent of the interrogation signals when:
 - (1) The two pulses P₁ and P₃ constituting an interrogation are of equal amplitude and P₂ is not detected; and
 - (2) The amplitude of these signals received at the antenna end of the transmission line of the transponder is nominally 71 db below 1 milliwatt with limits between 69 and 77 db below 1 milliwatt.

Note: For this MTL requirement, a nominal 3 db transmission line loss and an antenna performance equivalent to that of a simple quarter wave antenna

are assumed. In the event these assumed conditions do not apply, the MTL of the installed transponder system must be comparable to that of the assumed system.

- b. The variation of the minimum triggering level between modes **shall not** exceed 1 db for nominal pulse spacings and pulse widths.
- c. The reply characteristics **shall** apply over a received signal amplitude range between minimum triggering level and 50 db above minimum triggering level.
- d. The suppression characteristics **shall** apply over a received, .signal amplitude range between 3 db above minimum triggering level and 50 db above minimum triggering level.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.8:

(1) Interrogate the transponder with Mode 3/A interrogation pulse signals described in Appendix A at a repetition rate of 500 interrogations per second. Adjust P1 and P3 equal in amplitude (no P2 pulses) and apply a signal level known to be below minimum triggering level. Increase the signal generator output level until the transponder reply rate is 450 replies per second. This is the transponder minimum triggering level (MTL). The installed system MTL (including transmission line loss) should be between 69 and 77 db below 1 milliwatt.

EXAMPLE :	Transponder MTL	-74 dbm
	Transmission Line Loss	3 db
	System MTL	-71 dbm

- (2) Repeat step (1) above using interrogation pulse signals described in Appendix A for Mode C. The variation in MTL between steps (1) and (2) should not exceed 1 db.
- (3) Repeat Paragraph §2.4.5.1, "Reply," and steps (1) through (4) but with selected interrogation levels of 3, 10, 25, and 50 db above the receiver minimum triggering level.
- (4) Repeat Paragraph §2.4.5.2, "No Reply," but with selected interrogation levels of 3, 10, 25, and 50 db above the receiver minimum triggering level.

2.4.6.2 Verification of Pulse Duration Discrimination (§2.2.6.2)

Purpose/Introduction:

a. Signals of received amplitude between minimum triggering level and 6 db above this level, and of a duration less than 0.3 microsecond at the antenna, **shall** not cause the transponder to initiate more than 10% reply or suppression action.

b. With the exception of single pulses with amplitude variations approximating an interrogation, any single pulse of a duration more than 1.5 microseconds **shall not** cause the transponder to initiate reply or suppression action over the signal amplitude range of minimum triggering level to 50 db above minimum triggering level.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.9:

- (1) Interrogate the transponder with Mode 3/A interrogations at a repetition rate of 500 interrogations per second. Adjust P_1 and P_3 (no P_2 pulse) to a width of 0.3 microseconds and set the RF level to 6 db above minimum triggering level. The reply efficiency should not exceed 10%.
- (2) Interrogate the transponder with Mode 3/A interrogations at a repetition rate of 500 interrogations per second. Adjust the RF level of P₁, P₂ and P₃ to 6 db above minimum triggering level. Reduce the width of P₂ to 0.3 microseconds. The reply efficiency should not be less than 90%.
- (3) Interrogate the transponder with a single input pulse at 1030 MHz. Vary the pulse width of the interrogation signal from 1.5 to 22 microseconds at input signal levels of 3, 10, 25, and 50 db above MTL. At each input signal, verify that the transponder does not reply to, and/or is not suppressed by, the interrogation signal.

2.4.7 Verification of Desensitization and Recovery Characteristics (§2.2.7)

2.4.7.1 Verification of Dead Time (§2.2.7.1)

Purpose/Introduction:

After reception of a proper interrogation, the transponder **shall** not reply to any other interrogation at least for the duration of the reply pulse train. This dead time **shall** end no later than 125 microseconds after the transmission of the last reply pulse of the group.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.6: In the absence of P₂ pulses, interrogate the transponder on Mode 3/A at a repetition rate of 500 interrogations per second and at a signal level at least 3 db above the receiver minimum triggering level. Using a second signal source (set to a comparable output level) with the interrogation rate synchronized with the first but delayed more than 150 microseconds, interrogate the transponder on Mode C. Gradually shorten the delay until the replies to the Mode C interrogations disappear. Note the interval between the SPI pulse of the Mode 3/A reply and the first framing pulse of the Mode C reply. The interval should be between 0 and 125 microseconds.

This test does not include a verification of the requirement in 2.2.7.1 b although it isn't clear how this requirement would be tested.

2.4.7.2 Verification of Echo Suppression and Recovery (§2.2.7.2)

Purpose/Introduction:

The transponder **shall** contain an echo suppression facility designed to permit normal operation in the presence of echoes of signals in space. The provision of this facility **shall** be compatible with the requirements for suppression of side lobes given in §2.2.5.3.

Measurement Procedures:

Not sure what this requirement means or how to test it.

Step 1: Brief descriptive title for this test step

2.4.7.2.1 Verification of Desensitization (§2.2.7.2.1)

<u>Purpose/Introduction:</u>

Upon receipt of any pulse more than 0.7 microseconds in duration, the receiver **shall** be desensitized by an amount that is within at least 9 db of the amplitude of the desensitizing pulse, but **shall** at no time exceed the amplitude of the desensitizing pulse, with the exception of possible overshoot during the first microsecond following the desensitizing pulse. Single pulses of duration less than 0.7 microseconds are not required to cause the specified desensitization, and **shall not** cause desensitization of duration greater than that permitted herein or by §2.2.7.2.2.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.10.1: Interrogate the transponder with Mode 3/A interrogation pulse signals described in Appendix A at a repetition rate of 500 interrogations per second. Precede P1 by 2.8 microseconds with a single 0.8 microsecond wide pulse at a signal level of 50 db above the receiver minimum triggering level. Adjust P1 and P3 equal in amplitude and increase the output to a level causing a reply rate of 450 replies per second. This level should be between 34 and 43 db above the receiver minimum triggering level.

2.4.7.2.2 Verification of Recovery (§2.2.7.2.2)

Purpose/Introduction:

Following desensitization, the receiver **shall** recover sensitivity (within 3 db of minimum triggering level) within 15 microseconds after reception of a desensitizing pulse having a signal strength up to 50 db above minimum triggering level. Recovery **shall** be nominally linear at an average rate not exceeding 3.5 db per microsecond.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.10.2: Note the signal levels required to just maintain 450 replies per second as the interval between the 0.8 microsecond pulse and P1 is gradually increased. Also note that the average rate does not exceed 3.5 db per microsecond as the signal level and interval is changed to just maintain the 450 pulses per second reply rate. At an interval of 15 microseconds, note that the sensitivity returns to at least -47 dbm. This last value should be changed to 3dB above the transponders MTL.

<u>Note:</u> An interval corresponding to a normal Mode 3/A interrogation and a side lobe interrogation is excluded.

2.4.7.3 Verification of Reply Rate (§2.2.7.4)

Purpose/Introduction:

- a. For equipment intended for installation in aircraft which operate at altitudes above 15,000 feet, the transponder **shall** be capable of at least 1,200 replies per second for a 15-pulse coded reply.
- b. For equipment intended for installation in aircraft which operate at altitudes not exceeding 15,000 feet, the transponder **shall** be capable of at least 1,000 replies per second for a 15-pulse coded reply.
- c. A sensitivity reduction type reply rate limit control **shall** be incorporated in the transponder. The range of this control **shall** permit adjustment, as a minimum, to any value between 500 and 2,000 replies per second, or to the maximum reply rate capability, if less than 2,000 replies per second, without regard to the number of pulses in each reply. Sensitivity reduction in excess of 3 db **shall not** take effect until 90 percent of the selected value is exceeded. Sensitivity reduction **shall** be at least 30 db for rates in excess of 150 percent of the selected value.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.12: Interrogate the transponder with a Mode 3/A signal at an RF level of 3 db above minimum trigger level. Adjust the interrogation rate at 1080 interrogations per second or 90% of the transponder's maximum reply rate whichever is less. The reply efficiency should not be less than 90%.

Increase the interrogation rate to 1800 interrogations per second or 150% of the transponder's maximum reply rate whichever is greater. The RF level to maintain 1080 or the transponder's maximum replies should be no less than 33 307 db above MTL.

2.4.8 Undesired Replies

The following test procedure should be 2.4.8.1 Random Triggering and Suppression Rate. It should also be decided if this type of test belongs here or maybe should be moved to section 3 Installed Equipment Performance.

2.4.8 Verification of Response in the Presence of Interference (§2.2.8)

Purpose/Introduction:

Installation in the aircraft **shall** be made in such a manner that, with all possible interfering equipments installed in the same aircraft operating in their normal manner on operational channels of maximum interference, but with the absence of bona fide interrogations, the random triggering rate (squitter) of the transponder **shall not** exceed 30 replies and/or suppressions per second as integrated over an interval equivalent to at least 300 random triggers, or 30 seconds, whichever is less.

Measurement Procedures:

Step 1: Brief descriptive title for this test step

2.4.9 Verification of Undesired Replies (§Error! Reference source not found.)

Purpose/Introduction:

See comment above.

Measurement Procedures:

Step 1: Brief descriptive title for this test step

2.4.9 This test and all subsequent tests should be re-numbered.

2.4.10 Verification of Transponder Self-Test and Monitor (§2.2.9)

2.4.10.1 Verification of Manual Self-Test (§2.2.9.1)

Purpose/Introduction:

- (1) When a manual self-test device is provided, it **shall** be limited to intermittent use by a spring loaded return-to-off switch, or equivalent.
- (2) The test interrogation rate **shall** not exceed 450 per second.
- (3) The lowest RF level at the input to the antenna required to accomplish the test **shall** be used. The maximum RF level at the input to the antenna **shall not** exceed 40 db below 1 milliwatt.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.18.1:

- (a) If the self-test or monitor device is of a type which radiates a signal, or interferes with transponder reply function during the test period, the actuating system must be designed to limit test operation to only that time when manipulated. A spring return rotary switch or push button is considered to be such a device.
- (b) The test interrogation rate may be measured on the bench using a suitable detector and counter. The interrogation rate averaged over a five-second interval should not exceed 450 interrogations per second.
- (c) The test signal level may be measured at the antenna end of the transmission line in the actual aircraft, or on the bench using a length of transmission line equal to that in the airplane. One way to measure the level is to adjust a second test transponder to just trigger at the prescribed radiation limit. Connect this test transponder to the transmission line and determine if it is triggered when the self-testing device of the first transponder is operated.

Note: Due to the close proximity of the units and because of the high signal level, the transmitter of the first transponder should be disabled. A calibrated attenuator should be placed in the transmission line between the transponders to prevent receiver damage.

2.4.10.2 Verification of Automatic Self-Test (§2.2.9.2)

A, b, c, d instead of numbered.

Purpose/Introduction:

- (1) When an automatic self-test device is provided, it **shall** be limited to use only in the absence of a valid ground interrogation. (A minimum period of 15 seconds will be sufficient to establish the absence of ground interrogations).
- (2) The maximum test time for the automatic self-test shall not exceed 0.1 second in any given 15-second interval.
- (3) The test interrogation rate shall not exceed 450 per second.
- (4) The lowest RF level at the input to the antenna required to accomplish the test **shall** be used. The maximum RF level at the input to the antenna **shall not** exceed 40 db below 1 milliwatt.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.18.2:

(a) Interrogate the transponder at a nominal interrogation rate of 100 interrogations per second. Stop the interrogations and, using a timing device (such as an

- oscilloscope) and a suitable RF detector at the transponder output, verify that no test transmissions occur for a period of 15 seconds after the interrogations cease.
- (b) With no external interrogations, observe the output of the RF detector and verify that the automatic self-test transmissions do not occur for more than 0.1 second in any given 15 second interval.
- (c) The test interrogation rate may be measured on the bench using a suitable detector and counter. The interrogation rate averaged over a five second interval should not exceed 450 interrogations per second.
- (d) The test signal level may be measured at the antenna end of the transmission line in the actual aircraft, or on the bench using a length of transmission line equal to that in the airplane. One way to measure the level is to adjust a second test transponder to just trigger at the prescribed radiation limit. Connect this test transponder to the transmission line and determine if it is triggered when the self-testing device of the first transponder is operated.

<u>Note:</u> Due to the close proximity of the units and because of the high signal level, the transmitter of the first transponder should be disabled. A calibrated attenuator should be placed in the transmission line between the transponders to prevent receiver damage.

2.4.11 Verification of Response in Mutual Suppression Pulses (§2.2.10)

Purpose/Introduction:

If the equipment is designed to accept and respond to suppression pulses from other electronic equipment in the aircraft (to disable it while the other equipment is transmitting), the equipment must regain normal sensitivity within 3 db, not later than 15 microseconds after the end of the applied suppression pulse.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.11: If the transponder is provided with an external suppression jack, perform the following test:

Interrogate the transponder with a Mode 3/A signal at an RF level of 50 db above minimum triggering level at an interrogation rate of 500 pulses per second. Inject a suppression pulse into the external suppression jack. The pulse should have a width of 35 ± 10 microseconds, a rise-time of no less than 20 volts/microsecond, a fall time of no less than 10 volts/microsecond, and an amplitude of 18 volts. The leading edge of the suppression pulse, at the 0.5 amplitude point, should precede the leading edge of P1 by 2 ± 1.0 microseconds. The reply rate should not exceed five interrogations per second.

Delay the interrogation to 15 microseconds and note that the reply rate returns to 450 replies per second.

There is no defined requirement in section 2.2 for diversity. If there is no need for one, the following test procedure placeholder should be removed. If there is a need for a diversity requirement, it should be added and the corresponding test procedure be placed appropriately.

2.4.12 Verification of Diversity (§Error! Reference source not found.)

Purpose/Introduction:

Measurement Procedures:

Step 1: Brief descriptive title for this test step

2.4.13 Verification of Data Handling and Interfaces (§2.2.11)

This should be section 2.4.11 and should include verifying the reported mode A code with various code settings as currently in 2.4.13.2. The tests currently under 2.4.13.1 and 2.4.13.2 are really one test under 2.4.11.

2.4.13.1 Verification of Code Nomenclature (§2.2.11.1)

Purpose/Introduction:

Measurement Procedures:

Step 1: Brief descriptive title for this test step

2.4.13.2 Verification of Identification (§2.2.11.2)

Purpose/Introduction:

The 4096 codes specified in §2.2.4 **shall** be manually selectable for reply to interrogations on Mode 3/A.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.15.1: Mode 3/A reply coding can be checked by changing the Mode 3/A code number while monitoring the transmitted output with a demodulator probe and oscilloscope. Only the framing pulses, F₁ and F₂, will appear when all code numbers are set to zero. The twelve information pulses and the SPI pulse appear in the positions and pattern described in §2.2.4.

2.4.13.3 Verification of Pressure Altitude Transmissions (§2.2.11.3)

a through f instead of numbered.

Purpose/Introduction:

(1) Independently of the other modes and codes manually selected, the transponder **shall** automatically reply to Mode C interrogations.

(2) The reply to Mode C interrogations **shall** consist of the two framing pulses together with the information pulses specified in §2.2.4.

Update 3 as in 2.2.11.3.

(3) At as early a date as practicable, transponders **shall** be provided with means to remove the information pulses, but to retain the framing pulses when the provision of §2.2.1 3.3.(6) is not complied with, in reply to Mode C interrogation.

<u>Note:</u> The information pulses should be capable of being removed either in response to a failure detection system or manually at the request of the controlling agency.

- (4) The information pulses **shall** be automatically selected by an analog-to-digital converter connected to a pressure-altitude data source in the aircraft referenced to the standard pressure setting of 29.92 inches of mercury.
- (5) Pressure altitude **shall** be reported in 100-foot increments by selection of pulses as shown in Figure 1.
- (6) The digitizer code selected **shall** correspond to within ±125 feet, on a 95 percent probability basis with the pressure altitude information (referenced to the standard pressure setting of 29.92 inches of mercury) used on board the aircraft to adhere to the assigned flight profile.

Measurement Procedures:

Originally from DO-144 §2.3.2.1.15.2:

- (a) Transponder response to Mode C interrogations may be monitored with a demodulator probe and an oscilloscope. A Mode C reply without the digitizer connected to the transponder should consist of the two framing pulses F1 and F2.
- (b) The altitude reporting switch in the "off" position should prevent the transmission of digitizer information pulses but not the transmission of the framing pulses.
- (c) If a digitizer is connected to the transponder, the information pulses will appear in accordance with the pattern represented in Figure 1.

Include figure 1.

Replace the following test procedure placeholder with 2.4.12 Emission of Spurious Energy Test.

2.4.14 Verification of ATCRBS Transponder (§2.2.12)

Purpose/Introduction:

Measurement Procedures:

Step 1: Brief descriptive title for this test step

Aren't these installed equipment tests? .

2.4.15 Antennas (§2.2.13)

2.4.15.1 Verification of Frequency (§2.2.13.1)

Purpose/Introduction:

The center frequency of the reply transmission **shall** be 1090 MHz. The frequency tolerance **shall** be ± 3 MHz.

Measurement Procedures:

Originally from DO-144: Interrogate the transponder and verify that the reply frequency is 1090 ± 3 MHz.

2.4.15.2 Verification of Impedance and VSWR (§2.2.13.2)

Purpose/Introduction:

Measurement Procedures:

Step 1: Brief descriptive title for this test step

2.4.15.3 Verification of Polarization (§2.2.13.3)

Purpose/Introduction:

Polarization of the reply transmissions **shall** be predominantly vertical.

Measurement Procedures:

Originally from DO-144: An inspection of the antenna system should affirm that radiation will be predominately vertically polarized.

An antenna system which produces vertically polarized radiation will be considered to have complied with this paragraph if it is mounted on the aircraft so that its polarization axis lies within an angle of 15° from the true vertical in level flight attitude.

2.4.15.4 Verification of Radiation Pattern (§2.2.13.4)

Purpose/Introduction:

Measurement Procedures:

Step 1: Brief descriptive title for this test step

2.4.16 Verification of Power (§2.2.14)

2.4.16.1 Verification of Cold Start (§Error! Reference source not found.)

Purpose/Introduction:

Measurement Procedures:

Step 1: Brief descriptive title for this test step

2.4.16.2 Verification of Interruption (§2.2.14)

Purpose/Introduction:

Measurement Procedures:

Step 1: Brief descriptive title for this test step

DRAFT V0.4<u>5a</u> © 2007, RTCA, Inc.

This Page Intentionally Left Blank

© 2007, RTCA, Inc. DRAFT V0.4<u>5a</u>

3 INSTALLED EQUIPMENT PERFORMANCE

This section states the minimum acceptable level of performance for the equipment when installed in the aircraft. For the most part, installed performance requirements are the same as those contained in Section 2, which were verified through bench and environmental test. However, certain requirements may be affected by the physical installation (e.g., antenna patterns, receiver sensitivity, etc.) and can only be verified after installation. The installed performance limits stated below take in consideration these situations.

3.1 Equipment Installation

The airborne ATC transponder system should have been installed in the aircraft by the use of acceptable workmanship and engineering practices in an airworthy manner, and in accordance with the equipment manufacturer's recommendations as set forth in his equipment installation manual or other appropriate publication. To assure that the airborne ATC transponder system has been properly and safely installed in the aircraft, make a thorough visual inspection thereof and conduct a gross over-all operational/functional check of the system on the ground prior to flight.

3.1.1 Equipment Accessibility

Equipment controls and display(s) installed for in-flight operation **shall** be readily accessible from the normal seated position. The appropriate operator/crew members(s) **shall** have an unobstructed view of the display(s) when in the normal sitting position.

3.1.2 Inadvertent Turn Off

Appropriate controls **shall** be provided with adequate protection against inadvertent turn off.

3.1.3 Displays

All installed system displays **shall** be readily visible and readable from the crew member's normal position in all ambient lighting conditions for which system use is required.

Note: Visors, glareshields or filters may be an acceptable means of obtaining daylight visibility.

3.1.4 Aircraft Power Source

The voltage and voltage tolerance characteristics of the equipment **shall** be compatible with the aircraft power source of appropriate category as specified in RTCA/DO-160E.

3.1.5 Transmission Line(s)

The transmission line(s) connecting antenna(s) and transponder(s) **shall** have impedance, power handling and loss characteristics in accordance with the equipment manufacturer's specifications.

3.1.6 Antenna Location

a. Single Antenna

The antenna **shall** be installed on the bottom of the aircraft as close to the longitudinal axis of the aircraft as possible.

b. Diversity Transponder Installation

The top and bottom antennas **shall** be mounted as near as possible to the center line of the fuselage. Antennas **shall** be located so as to minimize obstruction to their fields in the horizontal plane.

Recommendation: The horizontal distance between the top and bottom antennas should not be greater than 7.6 meters.

<u>Note:</u> This recommendation is intended to support the operation of any diversity transponder (including cables) with any diversity antenna installation and still satisfy the requirement of §3.1.6 c.

c. Reply Delay of Diversity Transponders.

The total two-way transmission difference in mean reply delay between the two antenna channels (including the differential delay caused by transponder-to-antenna cables and the horizontal distance along the aircraft centerline between the two antennas) **shall** not exceed 0.130 microseconds for interrogations of equal amplitude. This requirement **shall** hold for interrogation signal strengths between MTL +3 dB and -21 dBm. The jitter requirements on each individual channel **shall** remain as specified for non-diversity transponders (see §Error! Reference source not found.).

<u>Note:</u> This requirement limits the total apparent jitter caused by antenna switching and by cable and antenna location delay differences.

3.1.7 Mutual Suppression

If other equipment is installed in the aircraft operating at or near 1030 and 1090 MHz, such as DME, the need for mutual suppression **shall** be determined. When mutual suppression is used, the requirements of §Error! Reference source not found. shall be met.

3.2 Conditions of Test

The conditions of test stated in the following subparagraphs are applicable to the equipment tests specified in Subsection §3.3. Ground tests may be used for all tests specified.

3.2.1 Power Input

Tests may be conducted using either the aircraft's electrical power distribution system or an appropriate external power supply.

3.2.2 Interference Effects

With the equipment energized from the aircraft's electrical power generating system, individually operate each of the other electrically operated aircraft equipment and systems to determine that no significant conducted or radiated interference exists. Evaluate all reasonable combinations of control settings and operating modes. Operate communication and navigation equipment on at least the low, high and one mid-band frequencies. If appropriate, repeat tests using emergency power source(s).

3.2.3 Environment

During the tests, the equipment **shall not** be subjected to environmental conditions that exceed those in RTCA/DO-160E as specified by the equipment manufacturer.

3.2.4 Adjustment of Equipment

Circuits of the equipment under test **shall** be properly aligned and otherwise adjusted in accordance with the manufacturer's recommended practices prior to application of the specified tests.

3.2.5 Warm-up Period

Unless otherwise specified, all tests **shall** be conducted after a warm-up period of not more than 15 minutes.

3.2.6 Radiation Pattern

The antenna **shall** have a radiation pattern that is essentially omni directional in the horizontal plane and have sufficient vertical beamwidth to assure proper equipment operation during normal aircraft maneuvers.

3.3 Test Procedures for Installed Equipment Performance

The test procedures set forth below are considered satisfactory in determining required installed equipment performance. Testing requirements are stated, in a manner that will make maximum use of bench test data while limiting flight tests to those requirements

which cannot be tested conveniently by other means. Although suggested test procedures are cited, it is recognized that other methods may be preferred by the installing activity. These alternate procedures may be used if the installing activity can show that they provide at least equivalent information. In such cases, the procedures cited herein should be used as one criterion in evaluating the acceptability of the alternate procedures.

Installed equipment performance tests confirm surveillance functions. Data link functions will be dealt with in a future document.

Current U.S. operating regulations require tests similar to those described herein be performed bi-annually to ensure against deterioration of performance. Since equipment installation requires initial performance of these tests, they are included herein.

3.3.1 Conformity Inspection

Visually inspect the installed equipment to determine the use of acceptable workmanship and engineering practices. Verify that all mechanical and electrical connections have been made properly and that the equipment has been installed and located in accordance with the manufacturer's recommendations.

3.3.2 Bench Tests

The equipment **shall** have been tested and certified by the equipment manufacturer to demonstrate compliance with the minimum requirements stated in Section §**Error! Reference source not found.**.0.

The transponder tests required below may be conducted using portable test equipment.

3.3.3 Reply Frequency

Interrogate the installed transponder and verify that the reply frequency of the system is 1090 ±3 MHz for aircraft operating below 15,000 feet, or 1090, ±1 MHz for aircraft operating above 15,000 feet.

3.3.4 Framing Pulse Spacing

Verify that the time interval between the leading edges of the two framing pulses is 20.3 ± 0.10 microseconds.

3.3.5 Reply Codes

a. Verify that all Mode 3/A reply pulses listed below in Table 3.3.5 are present.

Table 3.3.5: Mode 3/A Reply Pulses

Pulse	Position (microseconds)	4096 code for this pulse only
F1	0.00	
C1	1.45	0010
A1	2.90	1000
C2	4.35	0020
A2	5.80	2000
C4	7.25	0040
A4	8.70	4000
B1	11.60	0100
D1	13.05	0001
B2	14.50	0200
D2	15.95	0002
B4	17.40	0400
D4	18.85	0004
F2	20.30	
SPI	24.65	

b. Interrogate the transponder a sufficient number of times to verify that the correct 4096 code is transmitted. Use more than one 4096 code.

3.3.6 Pressure Altitude Transmissions

- a. Verify that the transponder response to Mode C interrogations consists only of framing pulses F1 and F2. If complete altitude reporting capability is provided, the altitude digitizer may not be connected to the transponder at the time of the test
- b. Verify that the transponder response to Mode C interrogations consists of only framing pulses F1 and F2 with the altitude switch in the "OFF" position.

3.3.7 Altitude Reporting Test

a. A sufficient number of test points **shall** be checked to ensure that the altitude reporting equipment and transponder perform their intended function through their entire range while ascending or descending. Tests of each altitude code segment of the encoder (2300, 2500, 3800, 4300, 4800, 6800, 14,800 and 30,800 if available) are sufficient to ensure proper operation of each altitude code segment of the encoder.

DRAFT V0.4<u>5a</u> © 2007, RTCA, Inc.

b. Verify that the correspondence value of the altimeter system is 125 feet or less.

3.3.8 Reply Pulse Width

Verify that the duration of the F1 and F2 pulses between the 0.5 amplitude points on the leading and trailing edge is 0.45, ± 0.10 microsecond with the transponder replying on Mode 3/A, code 0001, and code 7477.

3.3.9 Receiver Sensitivity

- a. Verify that for ATCRBS interrogations the receiver sensitivity of the system at the antenna end of the transmission line is -73, ± 4 dBm.
- b. Verify that for Mode S P_6 type interrogations the sensitivity of the equipment at the antenna end of the transmission line is -74 dBm, ± 3 dB.
- c. The minimum triggering level (MTL) of the transponder shall be such that replies are generated to 90 percent of the interrogation signals when:
 - (1) The two pulses P₁ and P₃ constituting an interrogation are of equal amplitude and P₂ is not detected; and
 - (2) The amplitude of these signals received at the antenna end of the transmission line of the transponder is nominally 71 db below 1 milliwatt with limits between 69 and 77 db below 1 milliwatt.
 - **Note:** For this MTL requirement, a nominal 3 db transmission line loss and an antenna performance equivalent to that of a simple quarter wave antenna are assumed. In the event these assumed conditions do not apply, the MTL of the installed transponder system must be comparable to that of the assumed system.
- d. The variation of the minimum triggering level between modes **shall** not exceed 1 db for nominal pulse spacings and pulse widths.
- e. The reply characteristics **shall** apply over a received signal amplitude range between minimum triggering level and 50 db above minimum triggering level.
- f. The suppression characteristics **shall** apply over a received, .signal amplitude range between 3 db above minimum triggering level and 50 db above minimum triggering level.

3.3.10 Transmitter Power Output

a. Verify that transponders operating at altitudes above 15,000 feet and/or at normal cruising speeds in excess of 175 knots have a peak pulse power at the antenna end of the transmission line of at least +21 dBW and not more than +27 dBW.

b. Verify that transponders intended for operation at altitudes not above 15,000 feet have a peak pulse power at the antenna end of the transmission line of at least +18.5 dBW and not more than +27 dBW.

3.3.11 Mode S Address

Verify that the 24-bit discrete address transmitted in the Mode S squitter is the Mode S address that has been assigned to this aircraft. (See Advisory Circular 20-131A for information regarding Mode S address assignment.)

3.3.12 Received Reply

Interrogate the equipment with its discrete address and verify received reply.

3.3.13 Airspeed Fixed Field

Interrogate the equipment to confirm the maximum airspeed report.

3.3.14 On-the-Ground Condition

Verify that the equipment correctly reports the "on-the-ground" condition. If it is feasible to simulate the airborne condition, verify that the equipment correctly reports an "airborne" condition.

Also verify that when the unit is in the "inhibit replies" condition (see §Error! Reference source not found..b), the transponder continues to generated Mode S squitters and replies to discretely-addressed Mode S interrogations (UF=0, 4, 5, 16, 20, 21, 24), but does not reply to ATCRBS, ATCRBS/Mode S All-Call or Mode S-Only All-Call interrogations.

If the unit is not in the "inhibit replies" condition verify that the transponder continues to generate Mode S squitters and to reply to ATCRBS, ATCRBS/Mode S All-C all or Mode S-Only All-Call and discretely-addressed Mode S interrogations (UF=0, 4, 5, 16, 20, 21, 24).

3.3.15 Diversity Antenna Installations

Verify that the antennas on the aircraft are no more than 7.6 meter (25 feet) apart in the horizontal plane. The cables **shall** be essentially of equal electrical length.

3.4 Flight Test Procedures

The following test procedures provide one means of determining installed equipment performance. Although specific test procedures are cited, it is recognized that other methods may be preferred by the installing activity. These alternate procedures may be used if they provide at least equivalent information. In such cases, the procedures cited herein should be used as one criterion in evaluating the acceptability of the alternate procedures. The equipment shall be tested to determine compliance with the minimum

DRAFT V0.4<u>5a</u> © 2007, RTCA, Inc.

requirements stated in §2.2. In order to meet this requirement, test results supplied by the equipment manufacturer or other proof of conformity may be accepted in lieu of bench tests performed by the installing activity.

This guidance material offers examples of flight test procedures for demonstration of selected performance functions. Flight demonstration of installed performance may be required by the aircraft operator or by airworthiness inspection agencies.

A schedule must be arranged with the area air traffic control facility so that a controller is available to observe the transponder reply and communicate with the test aircraft to confirm performance of the transponder.

Select a test area such that line-of-sight signal propagation is assured. Test maneuvers may include standard rate turns through 360 degrees, climbs and descents so that ATC can confirm valid return through normal flight attitudes. Verification of Ident codes selected and reported altitude response to Mode C should be checked.

3.4.1 Ground Pre-Flight Tests

Originally from DO-144 §2.3.2.2.1:

The following transponder characteristic should be determined and the performance level noted:

- (1) Random triggering of the transponder should not exceed 30 replies per second as integrated over an interval equivalent to at least 300 random triggers, or 30 seconds, whichever is less. This should be determined with all possible interfering equipments operating in their normal manner on operational channels of maximum interference, but with the absence of bona fide transponder interrogations. This test can be performed by using an RF detector sufficiently coupled to the antenna to count the rate of non-interrogated replies.
- (2) Receiver/Transmitter system characteristics should be assured by determining the attenuation constant of the installed coaxial transmission line and the characteristics of the antenna. Measure the length of transmission line and refer to suitable handbooks regarding the type of coaxial cable or the transponder manufacturer's equipment manual to determine the amount, of attenuation in decibels. Inspect the antenna system and carefully observe that the antenna is installed in accordance with the manufacturer's recommendations, and that there are no protrusions from the aircraft which will affect the efficiency of the antenna. The following examples are given to empirically determine the system compliance:

EXAMPLE #1:

Effective radiated power =ERP

$$ERP = P_T - L + G_A$$

Where: P_T = Power in dbw at the antenna terminal of the

transponder. (Refer to §2.3.2.1.14)

L = Transmission Line Loss $G_A = Antenna gain above isotropic$

Assume the following:

- a) The measured transmitter power at the transponder antenna terminal is 100 watts (+20 dbw). The measured receiver sensitivity is -71 dbm.
- b) 10 feet of RG-8/U = 0.9 db.
- c) Antenna gain is unity with respect to isotropic which results in 0 db.

Then:

Transmitted ERP =
$$20 - 0.9 + 0$$

= 19.1 dbw

Effective Receiver Sensitivity =
$$-71 + 0.9 - 0$$

= -70.1 dbm

This example would allow the system to operate in aircraft for altitudes not exceeding 15,000 feet.

EXAMPLE #2:

Assume the following:

- a) The measured transmitter power at the trans- ponder terminal is 29 dbw.
- b) 33 feet of RG-8/U = 3 db
- c) Antenna gain is unity with respect to isotropic which results in 0 db.

Then:

Transmitter ERP =
$$29 - 3 + 0$$

= 26 dbw

Effective Receiver Sensitivity =
$$-74 + 3 - 0$$

= -71 dbm

This example would allow the system to operate in aircraft intended to operate at all altitudes.

- (3) Automatic altitude reporting performance should be checked as follows with aircraft on the ground:
 - (a) Set the altimeter normally used to maintain flight altitude to 29.92 inches of mercury (1013.2 millibars).

- (b) Select 10 or more evenly-spaced altitude test points between zero (sea level) and the maximum operating altitude of the aircraft. Test each of these test points for increasing altitude and for decreasing altitude.
- (c) Apply pressure to the static system. If separate static systems serve altimeter and digitizer, apply identical pressures simultaneously to each. Approach each test point slowly, decreasing pressure for increasing altitude, and vice versa, until a transition to the test point value occurs in the digital output. Record the pilot's altimeter reading at the instant of transition in the digitizer.
- (d) The installation is acceptable if the altimeter normally used to maintain flight altitude corresponds with the output of the digitizer within 125 feet at each test point and within ± 62 feet at not less than 70 percent of the test points.
- (4) The performance characteristics of any equipment(s) functioning external to the transponder system shall be evaluated to determine that the algebraic cumulative effective dead time does not exceed the specified limits.

3.4.2 Operational Flight Tests

Originally from DO-144 §2.3.2.2.2:

- (1) Perform the flight test using an ATC facility and procedures. The flight should be conducted from the airport to approximately 25 miles from the ground facility. Put the aircraft through those maneuvers normally associated with take-off, climb, holding procedures, descent and final approach. Determine in the course of these maneuvers that the transponder performs its intended function and is suitable for use in the ATC system.
- (2) If the system includes altitude reporting and while performing (1) above, request ATC to monitor the altitude being reported by the transponder and compare with the altimeter being used to maintain flight altitude.
- (3) Request ATC to verify proper performance while operating on several different codes. Do not use codes 7700 or 7600, unless requested by ATC.

<u>Note:</u> It should be recognized that some aircraft attitudes with respect to the ground station will cause momentary loss of contact.

© 2007, RTCA, Inc. DRAFT V0.4<u>5a</u>

This Page Intentionally Left Blank

DRAFT V0.4<u>5a</u> © 2007, RTCA, Inc.

EQUIPMENT OPERATIONAL PERFORMANCE CHARACTERISTICS

4.1 Required Operational Performance Requirements

To ensure the operator that operations can be conducted safely and reliably in the expected operational environment, there are specific minimum acceptable performance requirements that shall be met. The following paragraphs identify these requirements.

4.1.1 Power Inputs

Prior to flight, verify that the equipment is receiving primary input power necessary for proper conditions.

4.1.2 Equipment Operating Modes

The equipment shall operate in each of its operating modes.

4.1.3 Continue with Other Operational Requirements as Necessary

4.2 Test Procedures for Operational Performance Requirements

Operation equipment tests may be conducted as part of normal pre-flight tests. For those tests that can only be run in flight, procedures should be developed to perform these tests as early during the flight as possible to verify that the equipment is performing its intended function(s).

4.2.1 Power Input

With the aircraft's electrical power generating system operating, energize the equipment and verify that electrical power is available to the equipment.

4.2.2 Equipment Operating Modes

Verify that the equipment performs its intended function(s) for each of the operating modes available to the operator.

4.2.3 Continue with Other Test Procedures

Continue with other test procedures to verify the requirements of paragraph 4.1.

This Page Intentionally Left Blank

DRAFT V0.4<u>5a</u> © 2007, RTCA, Inc.

Membership

RTCA Special Committee 209 Minimum Operational Performance Standards for

Air Traffic Control Radar Beacon System (ATCRBS) Airborne Equipment

Co-Chairs

Thomas Pagano FAA Technical Center Robert Saffell Rockwell Collins

Secretary

Gary Furr L-3 Communications, The Titan Group

Members and Advisors

Lt. Joseph Adelmann U.S. Air Force

Dominic Anello DoD AIMS Program Office

Mark Annee U.S. Navy
Raymond Bayh BAE Systems
Woody Rodo

Woody Bode Freestate Electronics

William Brodegard Avidyne Corp

Mark Cato Air Line Pilot Association

Robert Clarke Alion Sciece
Thomas Conklin U.S. Air Force
Andy Davis Trig Avionics Ltd.
John Doughty Garmin International

Robert Duffer Federal Aviation Administration

Dick Eckert ITT

Douglas Edsall U.S. Army
John Fisher U.S. Air Force
Robert Grappel MIT Lincoln Lab

Douglas Guetter L-3 Communications / ACSS

Ron Harris Freestate Electronics
Vic Hunsicker DoD AIMS Program Office
Andrew Leone Federal Aviation Administration

Angela Leurs EuroAvionics Navigation System GmbH

Robert Manning L-3 Communications

Peter Markus Federal Aviation Administration
Scott Moore Northern Airborne Technology Ltd.

Tom Mulkerin Associates Inc.

Peter Muraca Federal Aviation Administration

Miles Muramuto U.S. Air Force Jack Oehme U.S. Air Force

Richard Olson Federal Aviation Administration
Michael Penner Avidyne Safety Systems Group

Eric Potier Eurocontrol
Blane Rasch U.S. Air Force

Jeffrey Robinson U.S. Air Force

Dean Ryan Avidyne Corporation

Stuart SearightFederal Aviation AdministrationGu ShiminCARERI, Shanghai ChinaPeter SkavesFederal Aviation Administration

Boris Stallings U.S. Navy

William Thedford Consultant, U.S. Air Force
John Van Dongen Federal Aviation Administration

Nolan Van Foeken Garmin International

Leo Wapelhorst L-3 Communications, The Titan Group

DRAFT V0.4<u>5a</u> © 2007, RTCA, Inc.

Appendix A

SSR automatic pressure altitude transmission code (pulse position assignment)

Insert tables from ICAO Annex 10, Volume IV, Appendix to Chapter 3.

© 2007, RTCA, Inc. DRAFT V0.4<u>5a</u>